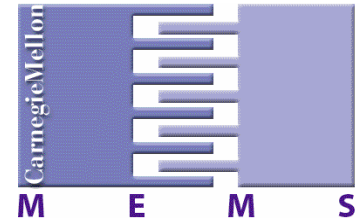




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APPLICATIONS OF BEHAVIORAL MODELING AND SIMULATION ON LAB-ON-A-CHIP: MICRO- MIXER AND SEPARATION SYSTEM

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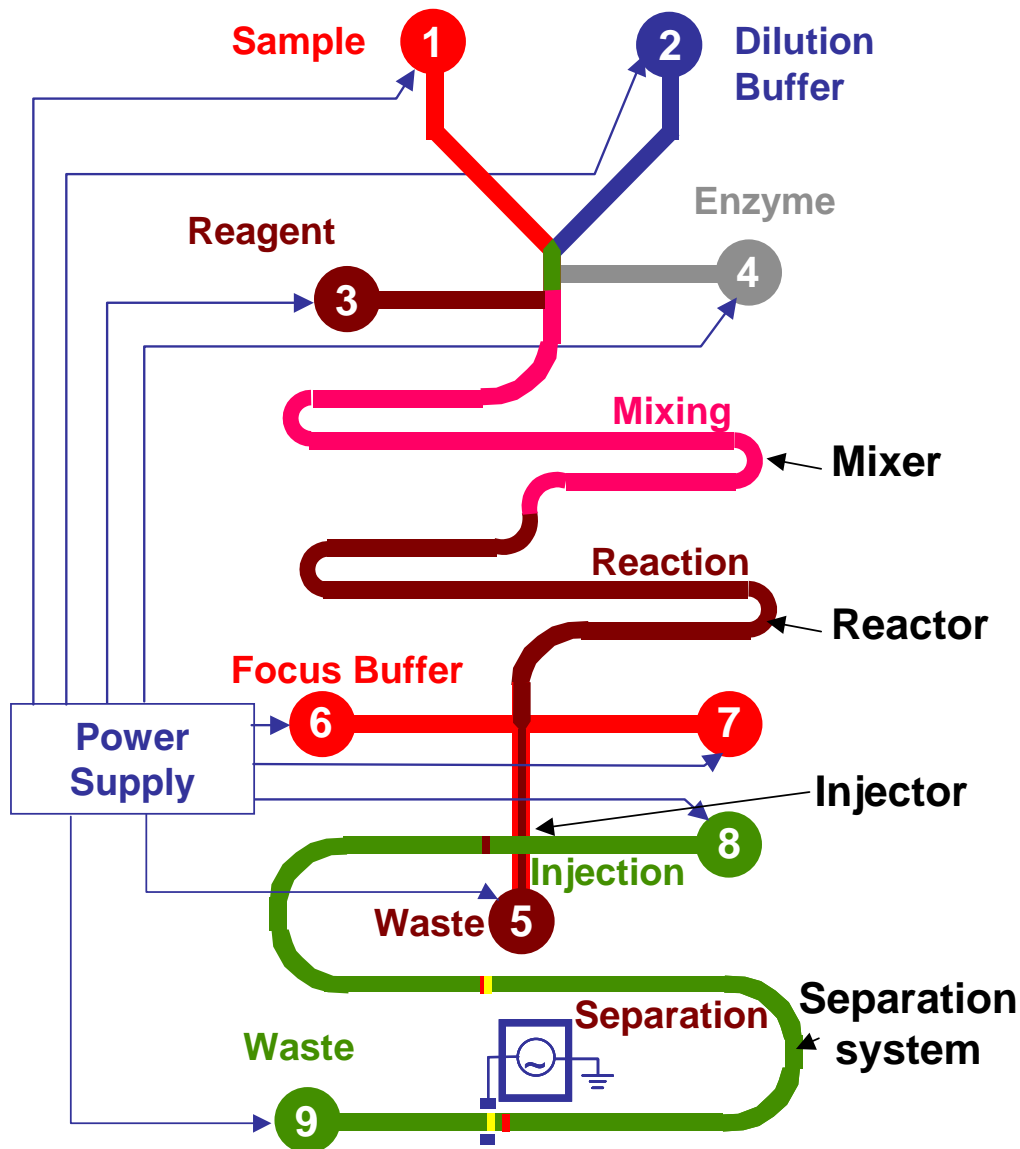
Carnegie Mellon University

<http://www.ece.cmu.edu/~mems>

Outline

- Introduction and Motivation
- Description of Model and Simulation Framework
- Composable System Simulation
- Summary

Introduction: Biofluidic Lab-on-a-chip



■ Biofluidic Lab-on-a-chip

- Sample saving
- Fast and parallel analysis
- High integration and automation

■ Four subsystems

- Mixer
- Reactor
- Injector
- separation system

■ Electrokinetic driven flow

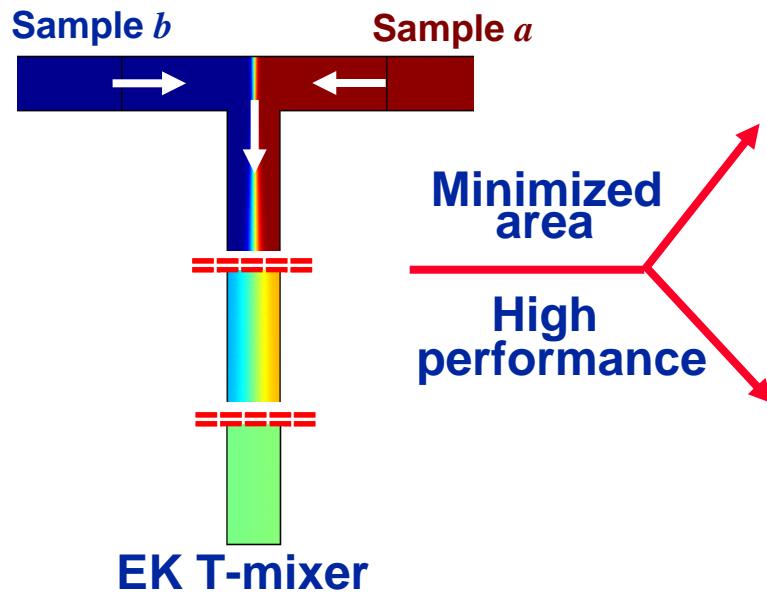
- Voltage control

Introduction: Electrokinetic Micromixers

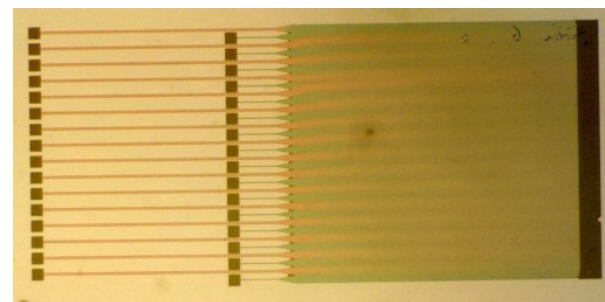
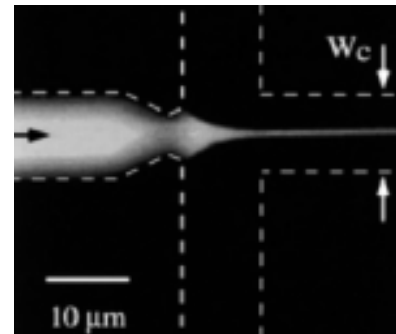
■ Mixing in Microscale

- Low Reynolds number and laminar flow
- Molecular diffusion dominant
- Enhancing techniques
 - Focusing
 - Multi-lamination...

Long mixing channel
Long mixing time



Focusing mixer
(Knight, J.B. et al.)



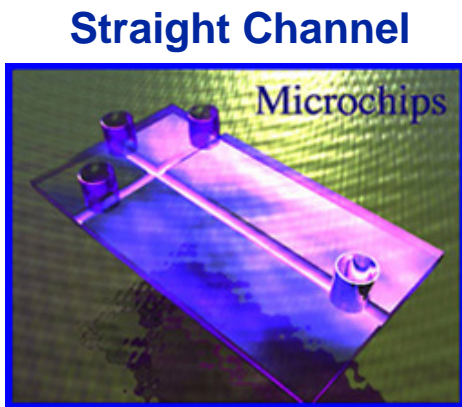
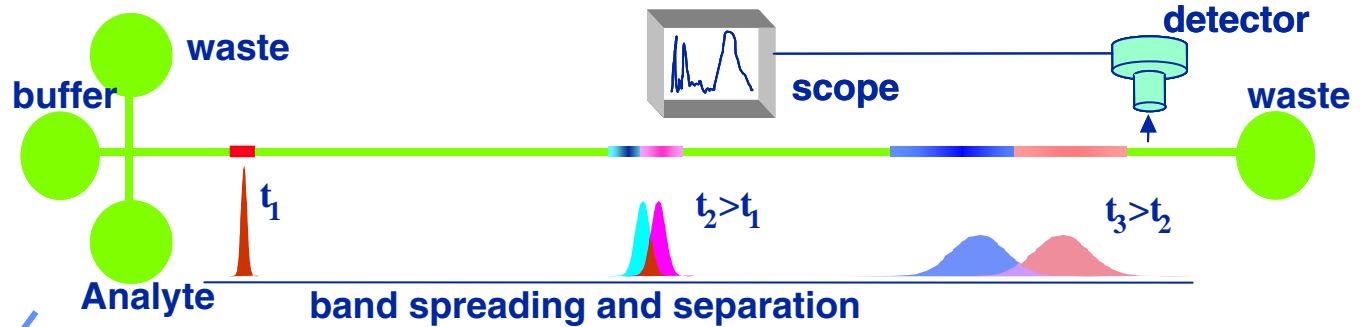
Multi-lamination mixer
(Koch, M. et al.)

- Complex topology geometry/network
- Extensive design space
- Arbitrary flow ratio
- Arbitrary inlet concentration

Introduction: Electrophoretic Separation

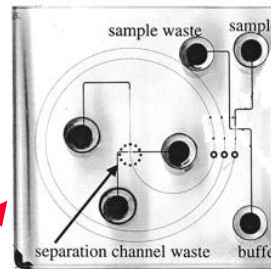
■ An important subsystem of lab on a chip

- Separation
- Detection

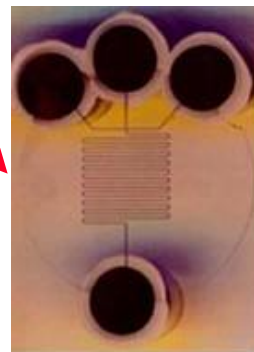


CE chip (ORNL)

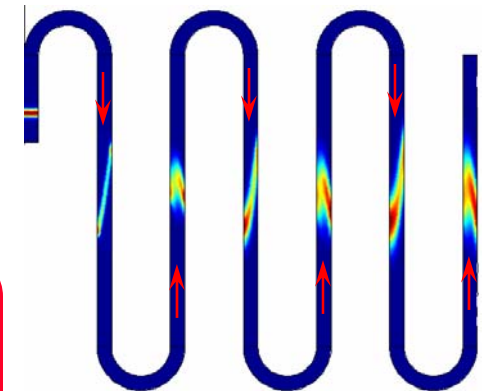
Minimized area
High performance



Spiral channel



Serpentine channel



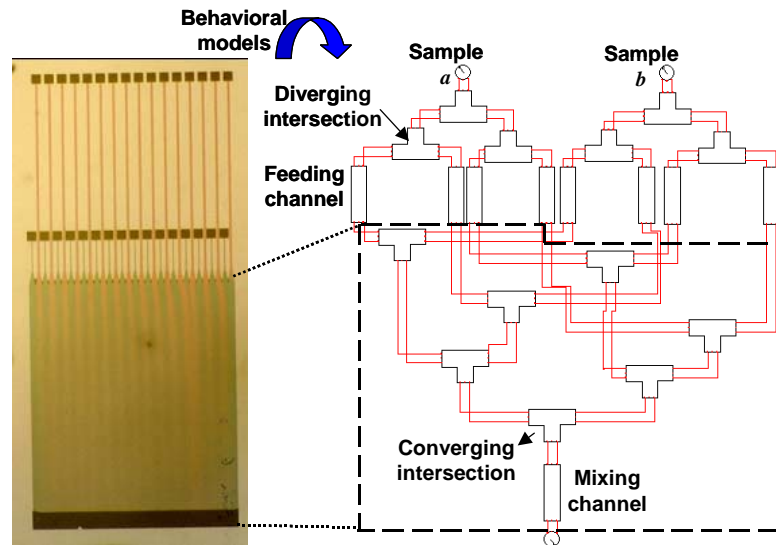
Band-broadening (dispersion)

Skew effect

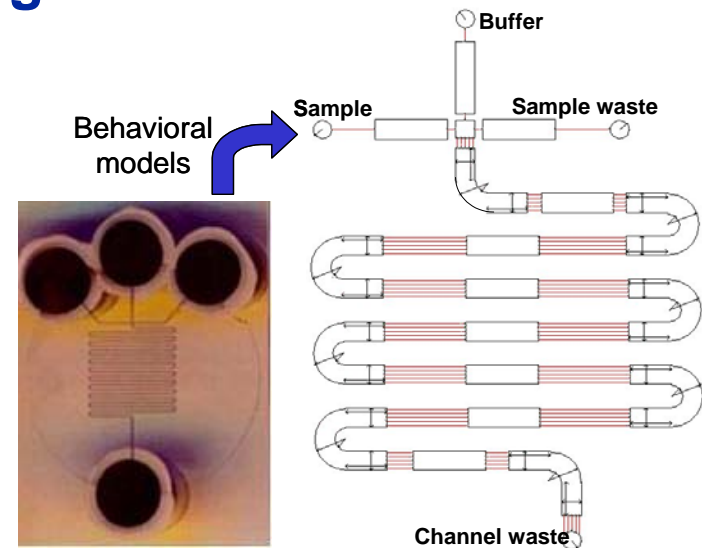
Interaction among channels

Method of Composable System Simulation

- A system decomposed into a set of behavioral models
 - Parameterized
 - Reusable
- Designs formed by interconnecting models



Multi-lamination mixer (Koch, M. et al.)



Serpentine separation chip (ORNL)

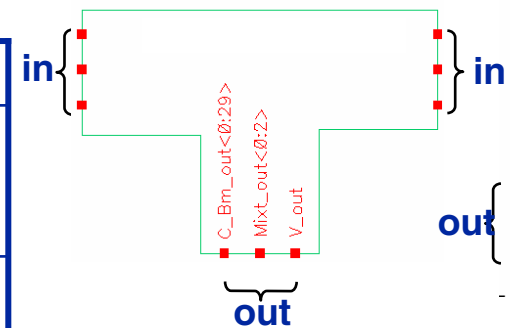
- Top-down analysis and design methodology
 - Fast and computationally robust
 - Hierarchical system design

Basic Element Models for Mixer

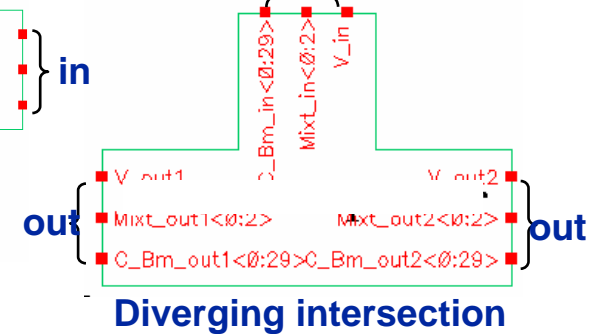
Basic element models

Name	Description
Converging Intersection	Concentration merged and compressed current converged
Diverging intersection	Concentration diverged, current diverged
Mixing straight Channel	Samples mixed along width-wise direction
Mixing turn	Elbow and U-turn of clockwise or counter-clockwise flow

Converging intersection

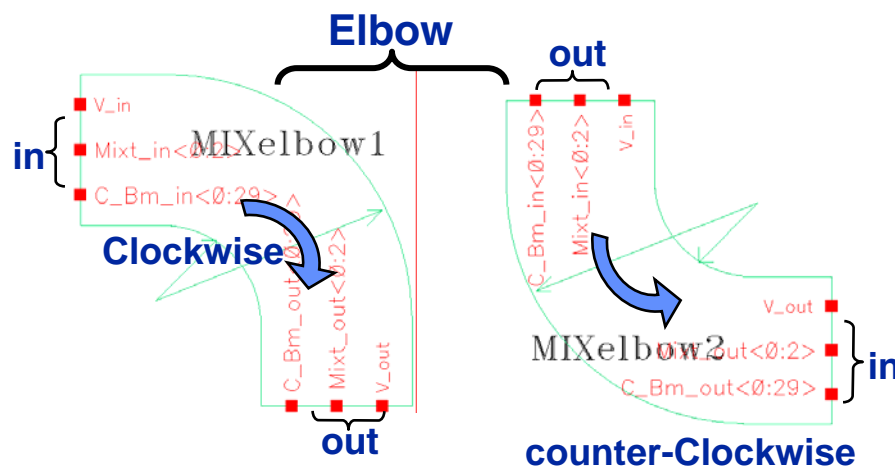
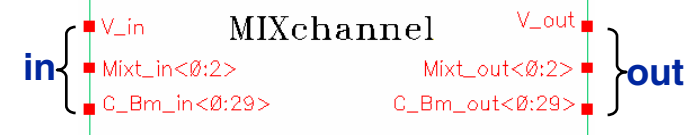


in



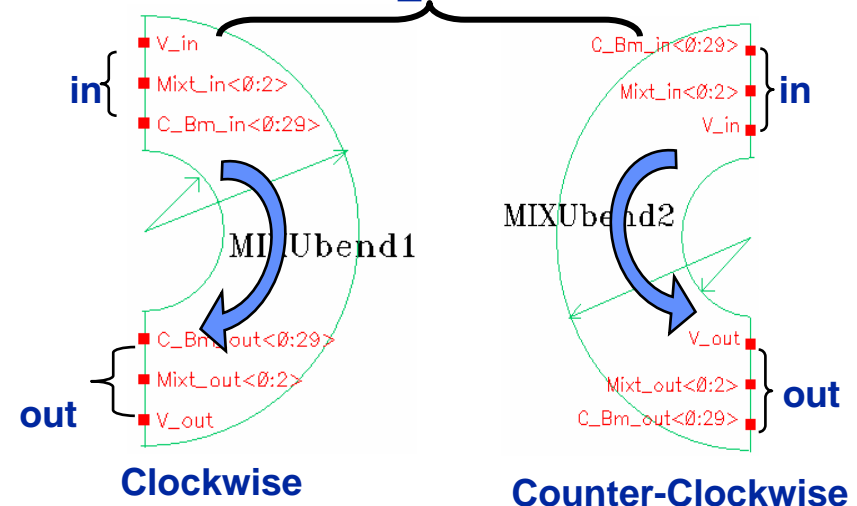
Diverging intersection

Straight Mixing Channel



counter-clockwise

U_turn

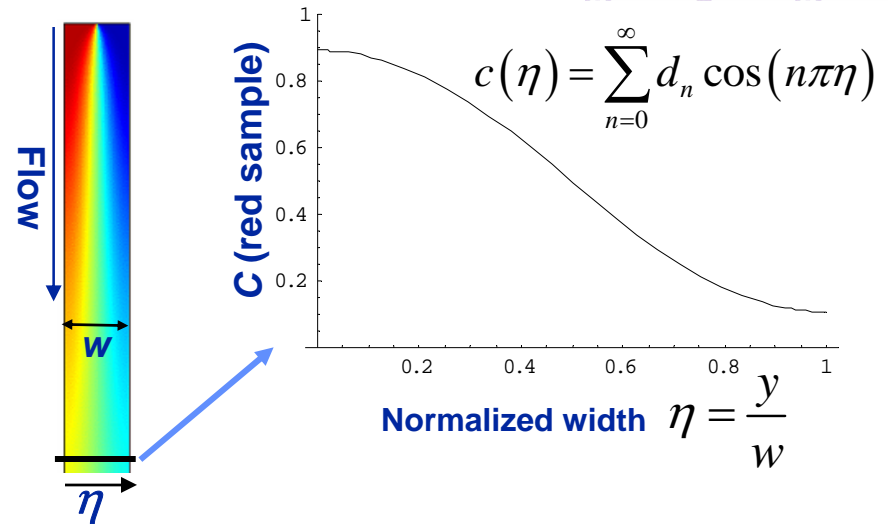


Clockwise

Counter-clockwise

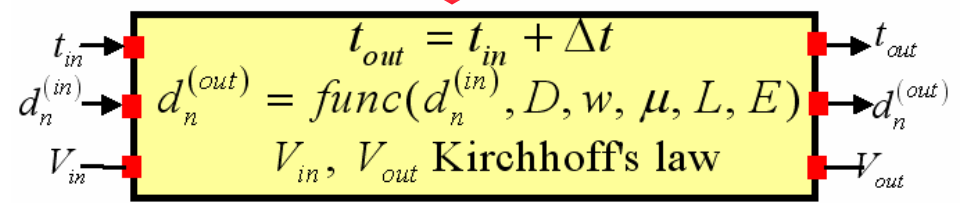
Interface Parameters

- **Interface parameters**
 - Mixing time (t)
 - Conc. coeff. (d_n)
 - Voltage (V)
- **Globally determined voltage**
- **Signal flow of fluidic interface parameters**
- **Starts from upstream-most sample reservoirs**
- **Simultaneous simulation of two or more samples in the buffer solvent**



User input

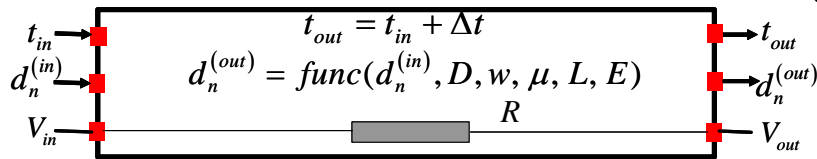
Component geometry (w, h, L)
mobility μ and diffusivity D



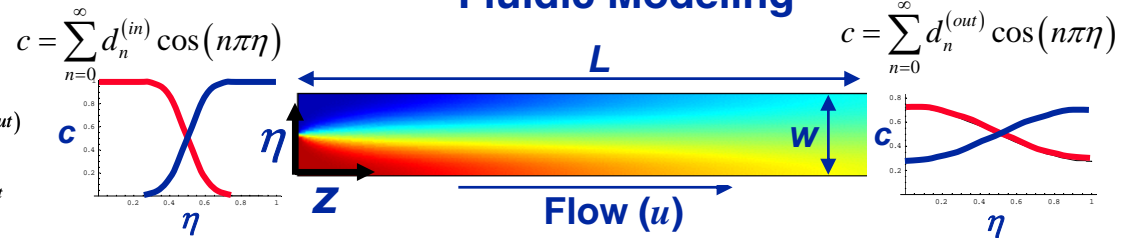
**Behavioral Model Structure
of Mixing Channel**

Model for Mixing Channels

Model Structure



Fluidic Modeling



Electric resistance and current

$$R = \frac{L\sigma}{wh} \rightarrow I = \frac{\Delta V}{R}$$

E-conductivity
Channel depth

Convection-diffusion equation

$$u \frac{\partial c}{\partial z} = \frac{D}{w^2} \frac{\partial^2 c}{\partial \eta^2}$$

Boundary conditions:

$$\left. \frac{\partial c}{\partial \eta} \right|_{\eta=0,1} = 0$$

$$c|_{z=0} = \sum_{n=0}^{\infty} d_n^{(in)} \cos(n\pi\eta)$$

Mixing Time

$$\Delta t = L/u \leftarrow \text{Sample electrokinetic velocity} \quad t_{out} = t_{in} + \Delta t$$

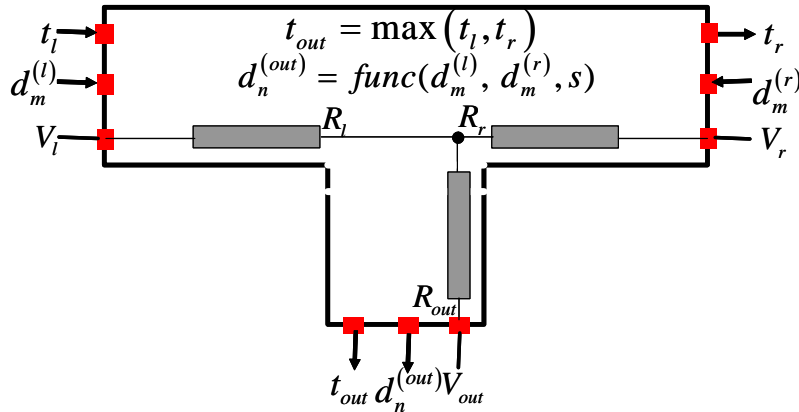
Concentration coefficients

$$d_n^{(out)} = d_n^{(in)} e^{-(n\pi)^2 \tau} \rightarrow \tau = \Delta t \cdot D / w^2$$

Dimensionless diffusion time Sample diffusivity

Model for Converging Intersections

Model Structure



■ Electric resistance and current

$$R_l = R_r = R_{out} = 0$$

$$I_{out} = I_l + I_r$$

■ Mixing Time

$$\Delta t = 0 \rightarrow t_{out} = \max(t_{in}^{(l)}, t_{in}^{(r)})$$

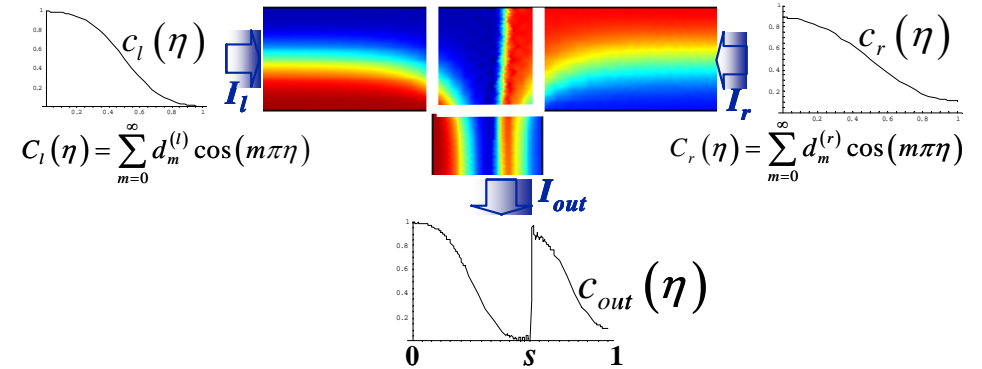
■ Concentration coefficients

$$\left\{ \begin{array}{l} d_0^{(out)} = d_0^{(l)} s + d_0^{(r)} (1-s) \\ d_{n \neq 0}^{(out)} = \sum_{m=0}^{m \neq ns} \left\{ 2(-1)^n d_m^{(r)} (1-s) \left(\cos(F_2/2) \sin(F_1/2) / F_1 + \cos(F_1/2) \sin(F_2/2) / F_2 \right) \right. \\ \quad \left. + d_m^{(l)} s \left(f_1 \sin(f_2) + f_2 \sin(f_1) \right) / f_1 f_2 \right\} + \sum_{m=ns}^{m=ns} \left(d_m^{(l)} s + d_m^{(r)} (-1)^m (1-s) \right) \end{array} \right.$$

$$f_1 = (m - ns)\pi \quad f_2 = (m + ns)\pi$$

$$F_1 = (m + n - ns)\pi \quad F_2 = (m - n + ns)\pi$$

Fluidic Modeling

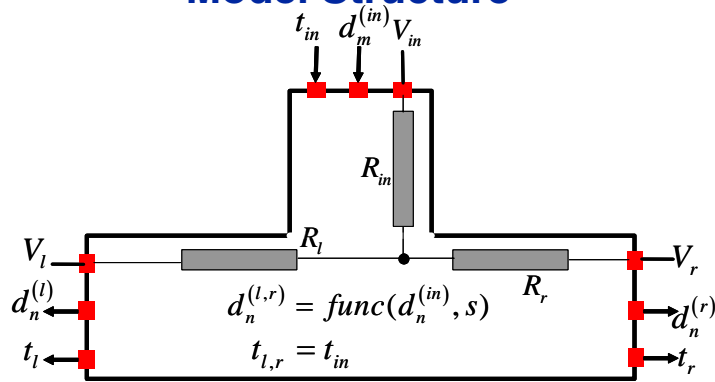


$$C_{out}(\eta) = \begin{cases} \sum_{m=0}^{\infty} d_m^{(l)} \cdot \cos\left(\frac{m\pi\eta}{s}\right), & 0 \leq \eta < s \\ \sum_{m=0}^{\infty} d_m^{(r)} \cdot \cos\left(\frac{m\pi(\eta-s)}{1-s}\right), & s \leq \eta < 1 \end{cases}$$

Interface position $s = I_l / (I_l + I_r)$

Model for Diverging Intersections

Model Structure



Electric resistance and current

$$R_l = R_r = R_{out} = 0$$

$$I_{in} = I_l + I_r$$

Mixing Time

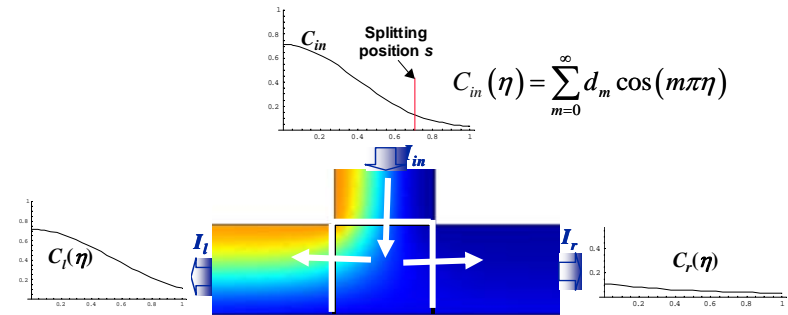
$$\Delta t = 0 \quad \rightarrow \quad t_l = t_r = t_{in}$$

Concentration coefficients

Left stream

$$\begin{cases} d_0^{(l)} = d_0^{(in)} + \sum_{m=1}^{\infty} d_m^{(in)} \sin(\phi_1) / \phi_1 \\ d_{n \neq 0}^{(l)} = 2 \sum_{m=0}^{m \neq n/s} d_m^{(in)} (-1)^{n+1} \phi_1 \sin(\phi_1) / f_1 f_2 \\ \quad + \sum_{m=0}^{m=n/s} d_m^{(in)} (1 + \sin(2\phi_1) / (2\phi_1)) \end{cases}$$

Fluidic Modeling



$$C_{in}(\eta) = \sum_{m=0}^{\infty} d_m \cos(m\pi\eta) \quad C_r(\eta) = \sum_{m=0}^{\infty} d_m \cos\left(m\pi(1-s)\left(\eta + \frac{s}{1-s}\right)\right)$$

Splitting position $s = I_l / (I_l + I_r)$

$$\begin{aligned} f_1 &= (m - ns)\pi & f_2 &= (m + ns)\pi \\ F_1 &= (m + n - ns)\pi & F_2 &= (m - n + ns)\pi \\ \phi_1 &= ms\pi & \phi_2 &= m(1-s)\pi \end{aligned}$$

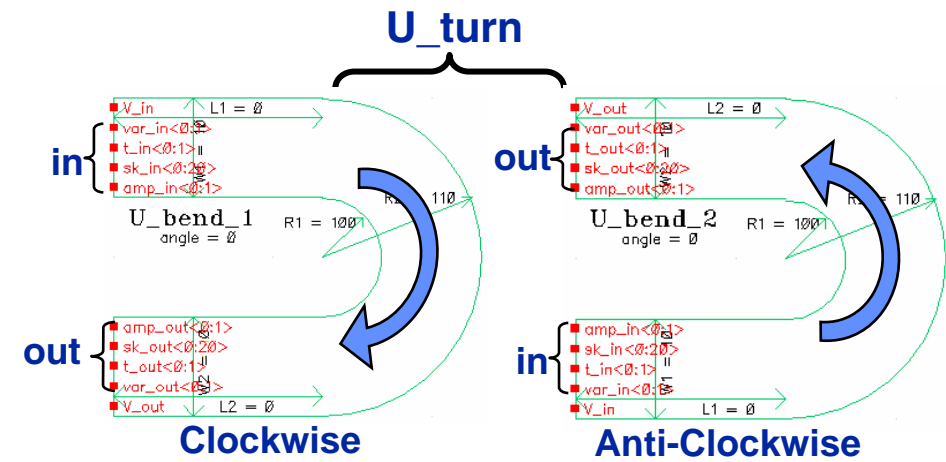
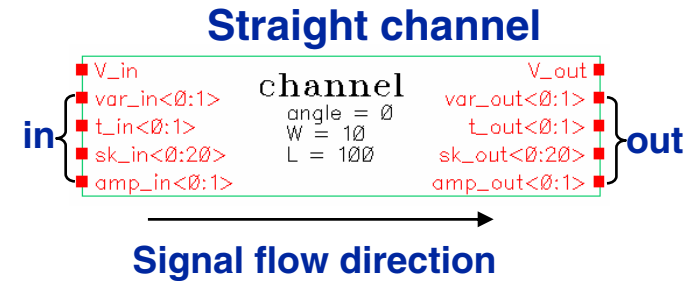
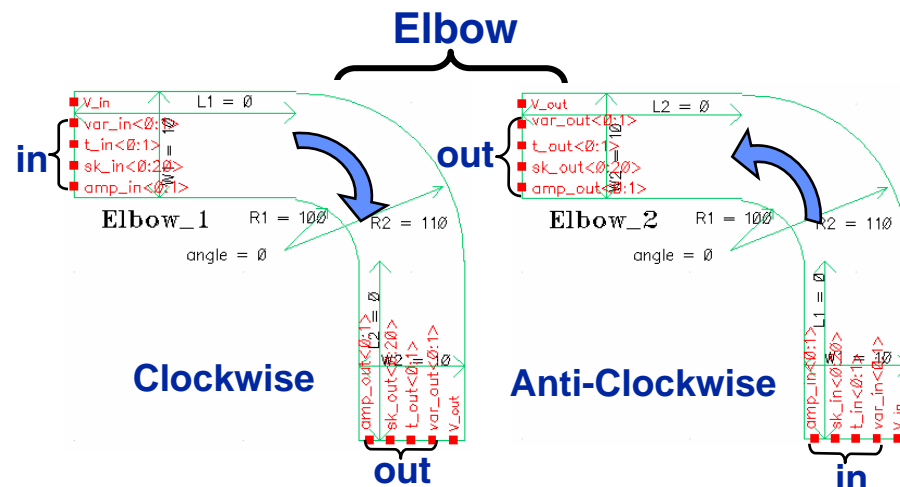
Right stream

$$\begin{cases} d_0^{(r)} = d_0^{(in)} - \sum_{m=1}^{\infty} d_m^{(in)} \sin(\phi_1) / \phi_2 \\ d_{n \neq 0}^{(r)} = 2 \sum_{m=0}^{m \neq n/(1-s)} d_m^{(in)} \phi_2 \sin(\phi_1) / F_1 F_2 \\ \quad + \sum_{m=0}^{m=n/(1-s)} d_m^{(in)} (\phi_2 \cos(\phi_1) - \sin(\phi_1)) / \phi_2 \end{cases}$$

Basic Models for Separation System

Basic behavioral models

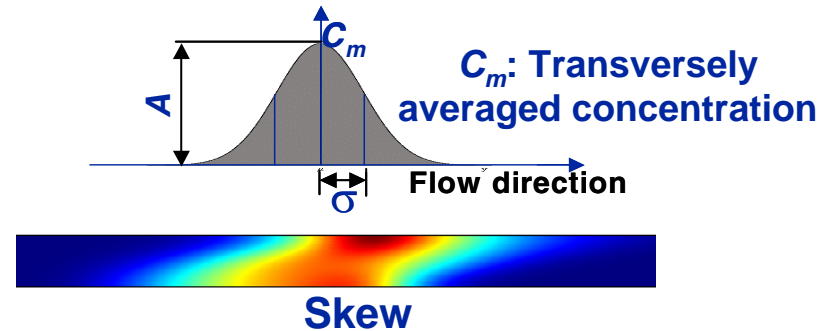
Name	Description
Channel	Straight Channel
elbow_1	Elbow of clockwise flow
elbow_2	Elbow of anti-clockwise flow
U_turn_1	Turn of clockwise flow
U_turn_2	Turn of anti-clockwise flow



Interface Parameters and Model Structure

Interface parameters

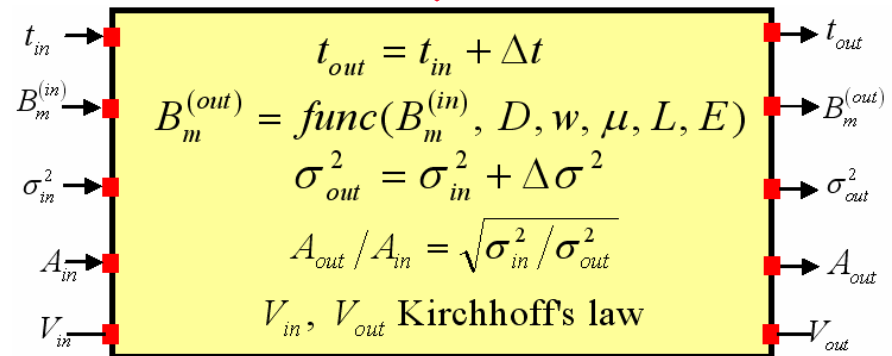
- Variance (σ^2)
- Separation time (t)
- Skew coefficients (B_m)
- Amplitude (A)
- Voltage (V)



- Globally determined voltage
- Signal flow of fluidic interface parameters
- Starts from injector
- Simultaneous simulation of two or more species in the analyte

User input

Component geometry (w, L, R_c)
mobility μ and diffusivity D



Behavioral Model Structure

Model: Separation Channels of Turn Geometry

■ Electrophoretic velocity

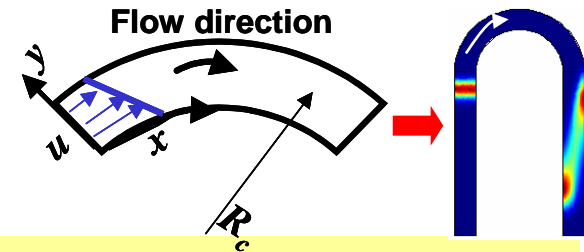
$$E = \Delta V / \theta R_c \rightarrow U = \mu E \rightarrow u \approx U \cdot \left(1 + \frac{(w - 2y)}{R_c}\right)$$

Species mobility

Non-uniform velocity

■ Variance

Input from upstream



$$\Delta \sigma^2 = 2w^2 \tau_t \pm Jw^2 \sum_{m=1,3,5\dots}^{\infty} \left(B_m^{(in)} \lambda_m (1 - e^{-\lambda_m \tau_t}) \pm J (\lambda_m \tau_t + e^{-\lambda_m \tau_t} - 1) / \lambda_m \right) / \lambda_m^3$$

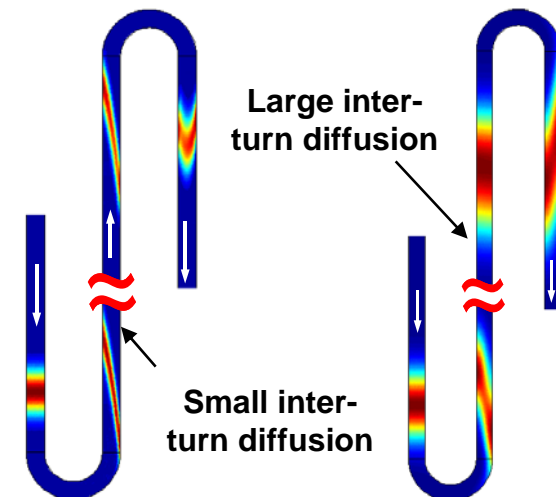
■ Skew coefficients

Input from upstream

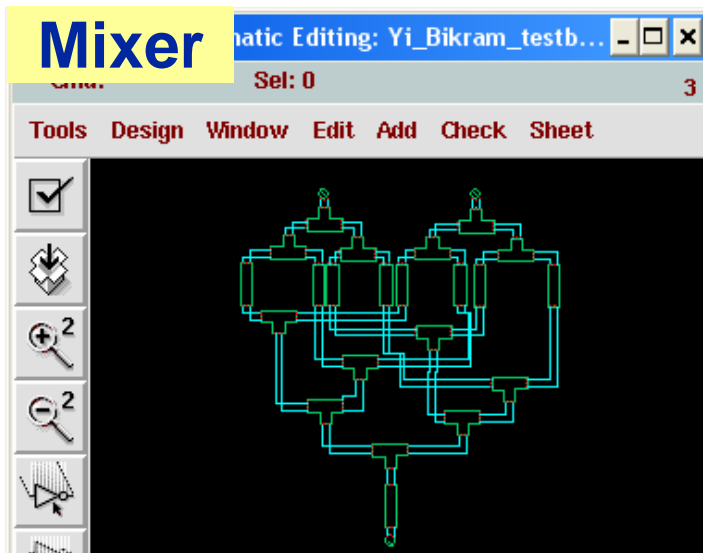
$$B_m^{(out)} = \pm J (1 - e^{-\lambda_m \tau_t}) / \lambda_m^2 + B_m^{(in)} \cdot e^{-\lambda_m \tau_t}$$

$$J = 8\theta / \tau_t \quad \lambda_m = (m\pi)^2$$

$$t = \theta R_c / U \quad \tau_t = t \cdot D / w^2$$

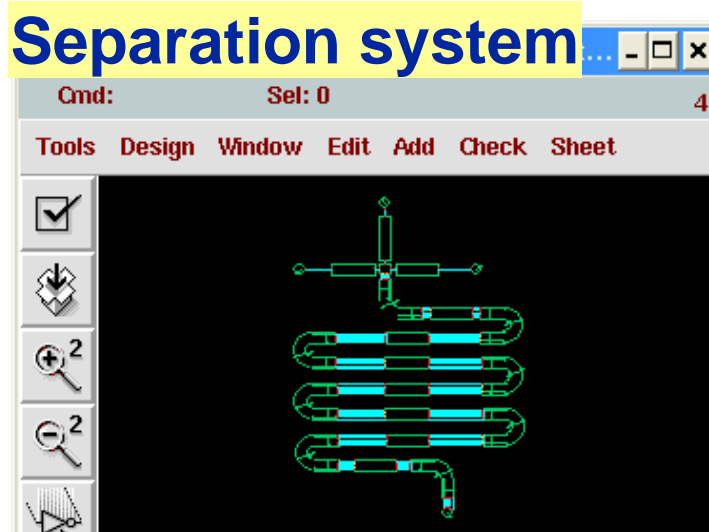


System Simulations



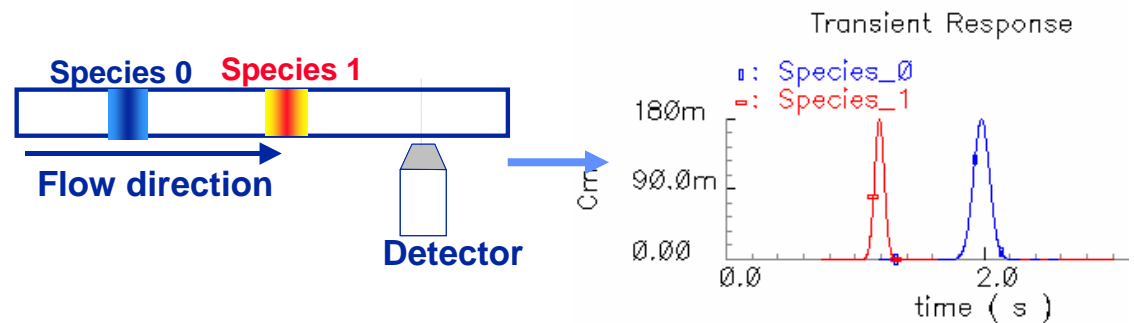
■ DC analysis

- Electric variable (voltage/current)
- Microfluidic simulation
 - Mixing time (t)
 - Conc. profile (d_n)
- Mixing performance



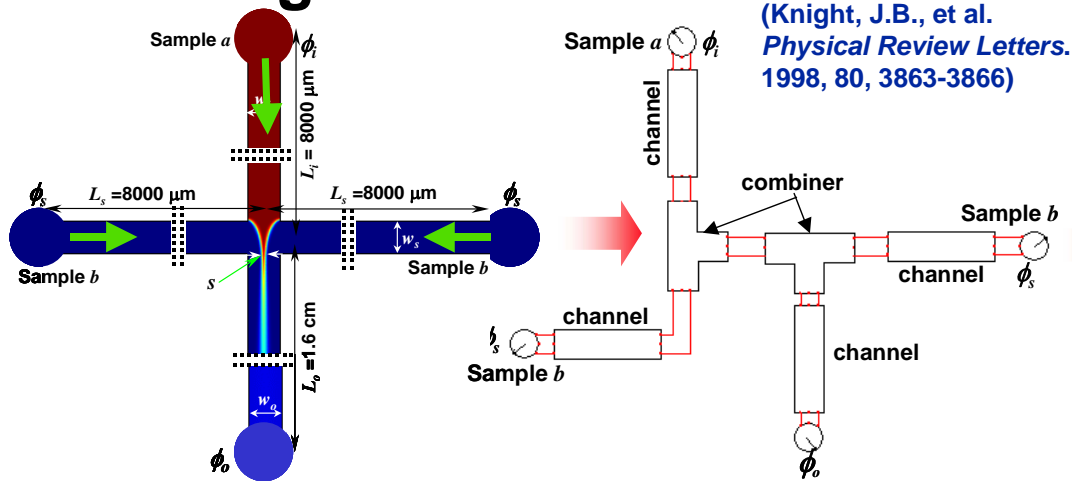
■ DC and Transient Analysis

- Resolution
- Electropherogram

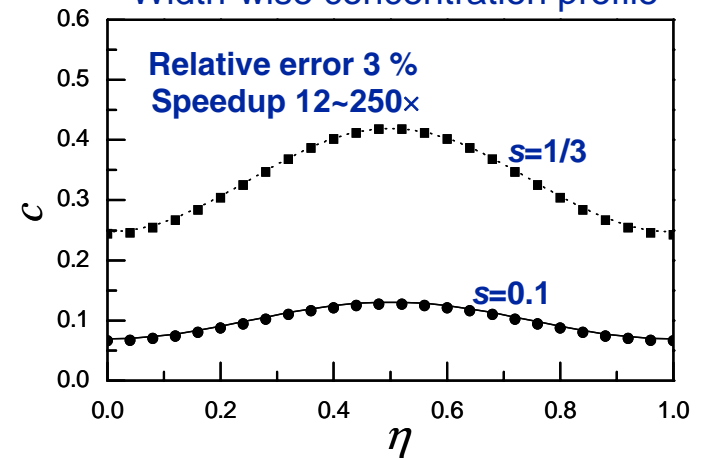


Verification: Focusing and Multi-stream Mixers

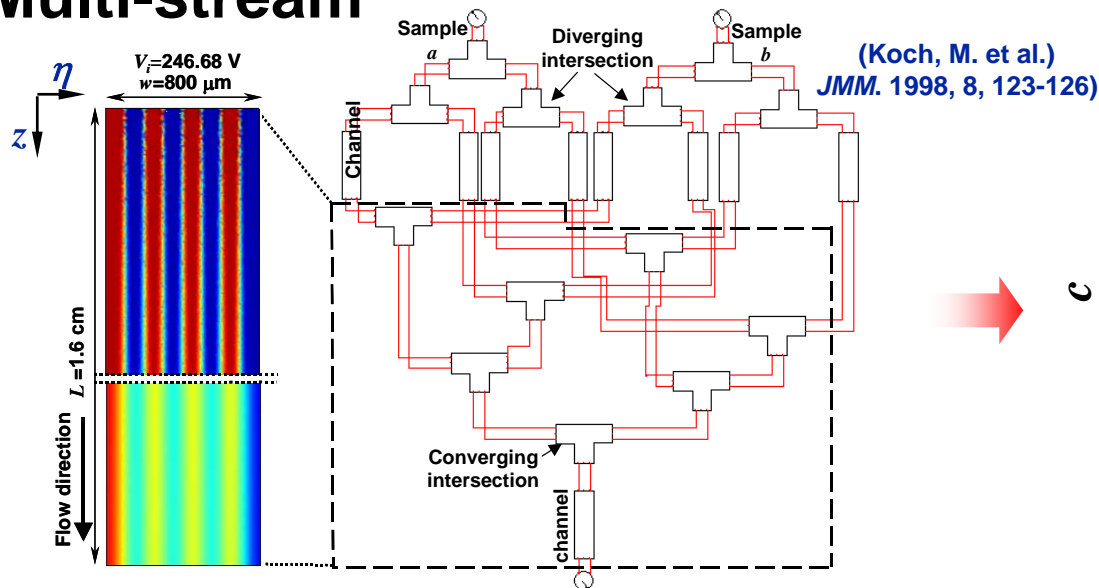
Focusing



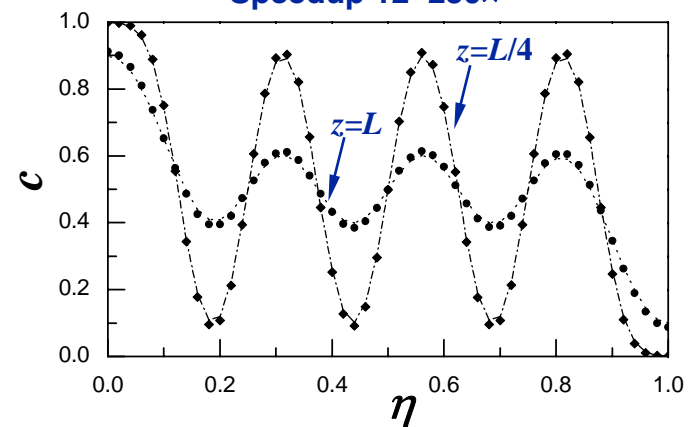
Width-wise concentration profile



Multi-stream



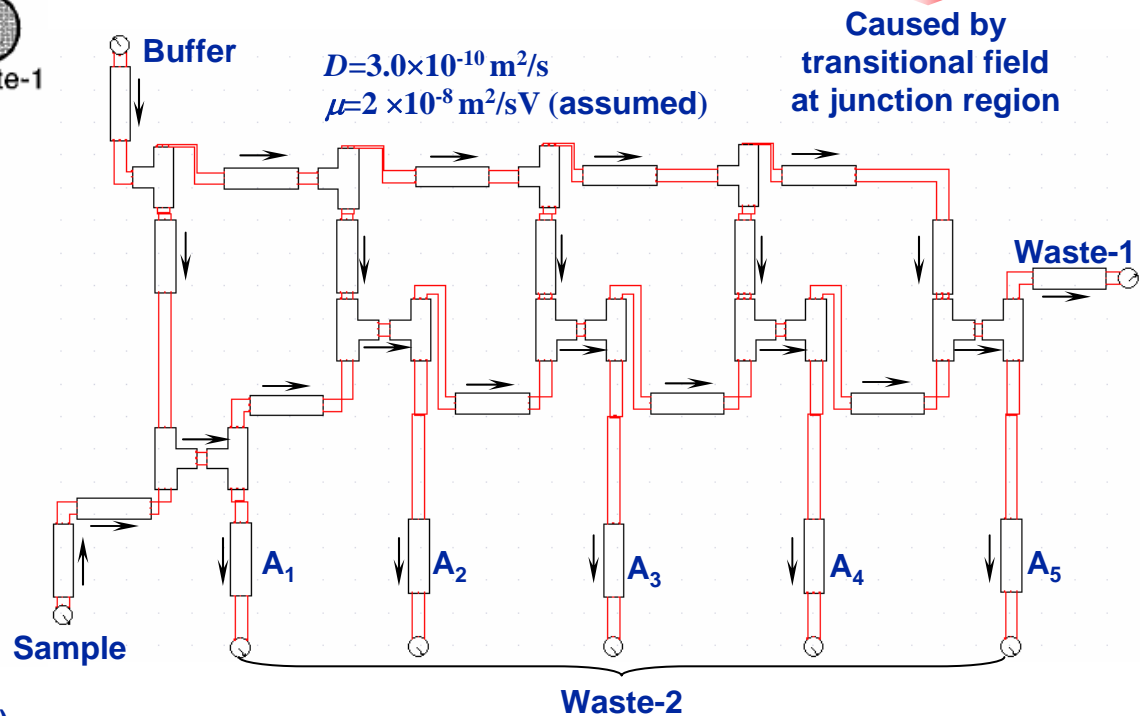
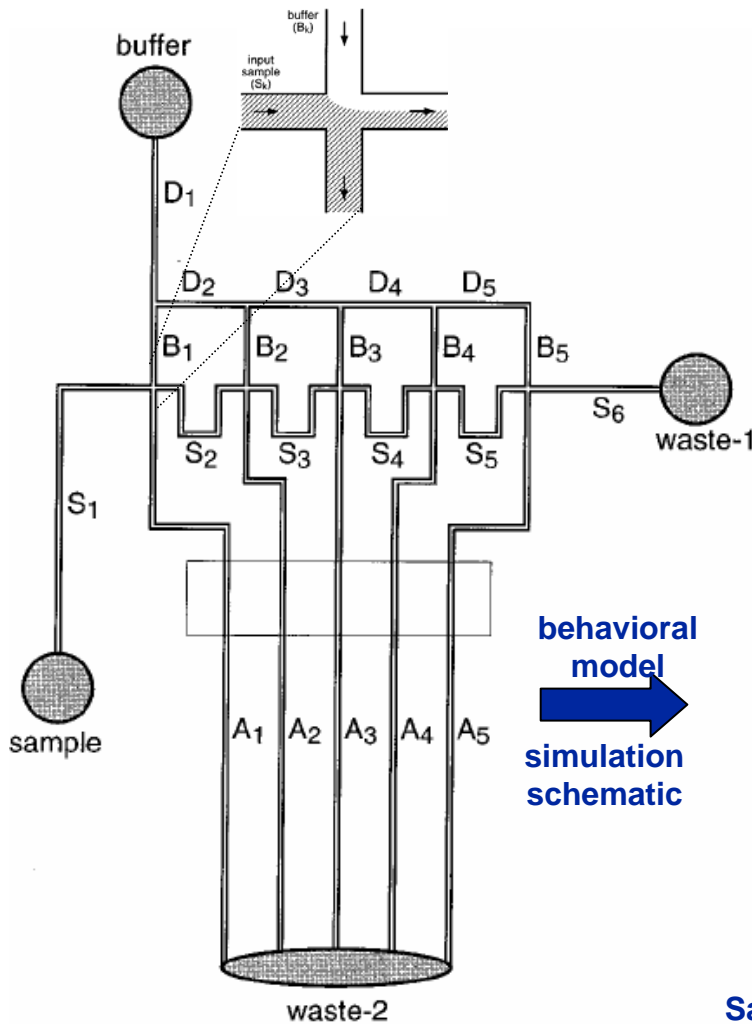
Relative error 3%
Speedup 12~250x



Verification: Serial Mixing Network

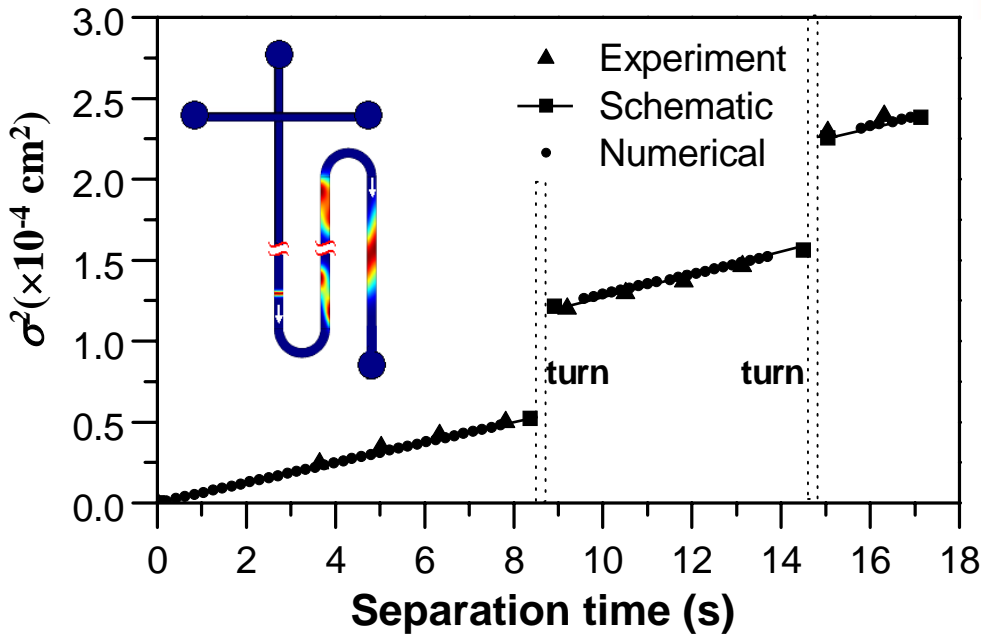
Concentration comparison

Channel	Complete mixing		Partial Mixing		
	Sche.	Exper.	Sche.	Num.	Error
A ₁	1.0	1.0	1.0	1.0	
A ₂	0.37	0.36	0.48	0.51	5.9%
A ₃	0.22	0.21	0.186	0.195	4.6%
A ₄	0.125	0.13	0.081	0.086	5.8%
A ₅	0.052	0.059	0.029	0.0315	7.9%

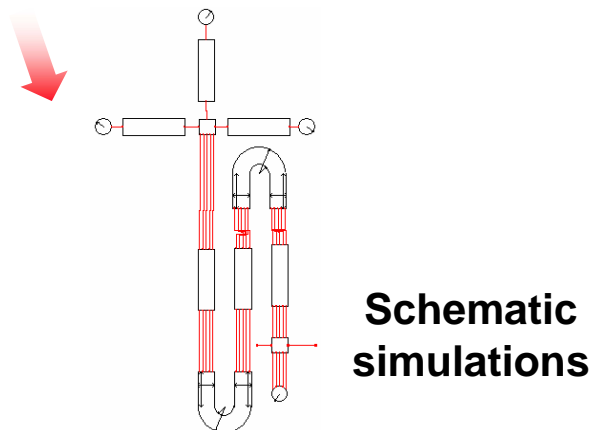


(Jacobson, S.C. et al. *Anal. Chem.* 1999, 71, 4455-4459)

Verification: Double Complimentary Turns

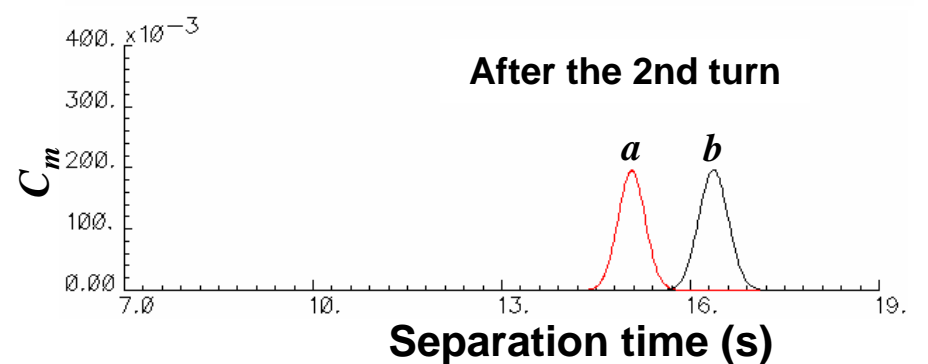
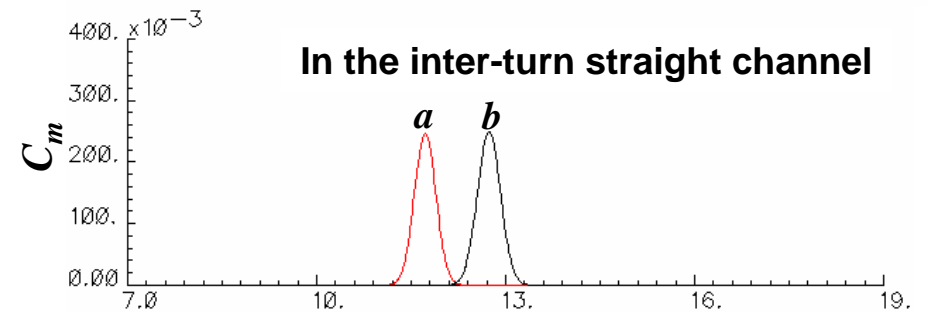
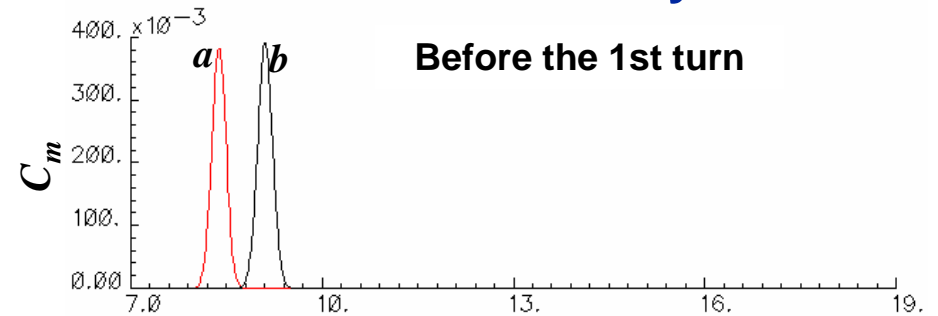


(C.T. Culbertson, S.C. Jacobson, J.M. Ramsey. *Anal. Chem.* 1998, 70, 3781-3789)



Worst relative error 5% Speedup 500~10,000x

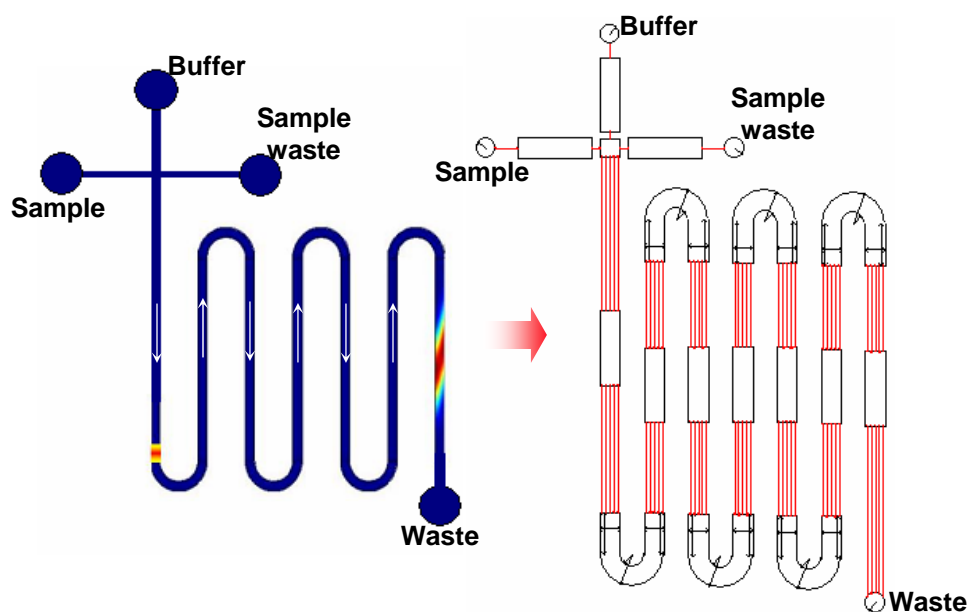
Transient Analysis



Verification: Multiple Turns

- Behavioral models used in complex EP system
- Good agreement and tremendous speedup

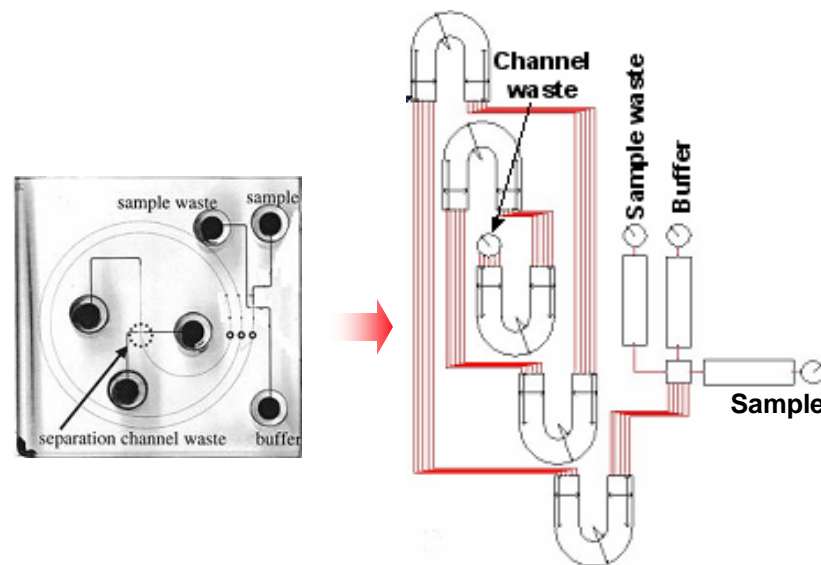
Serpentine of six turns



Worst relative error 9.5% compared with numerical simulation

Speedup 600~15,000×

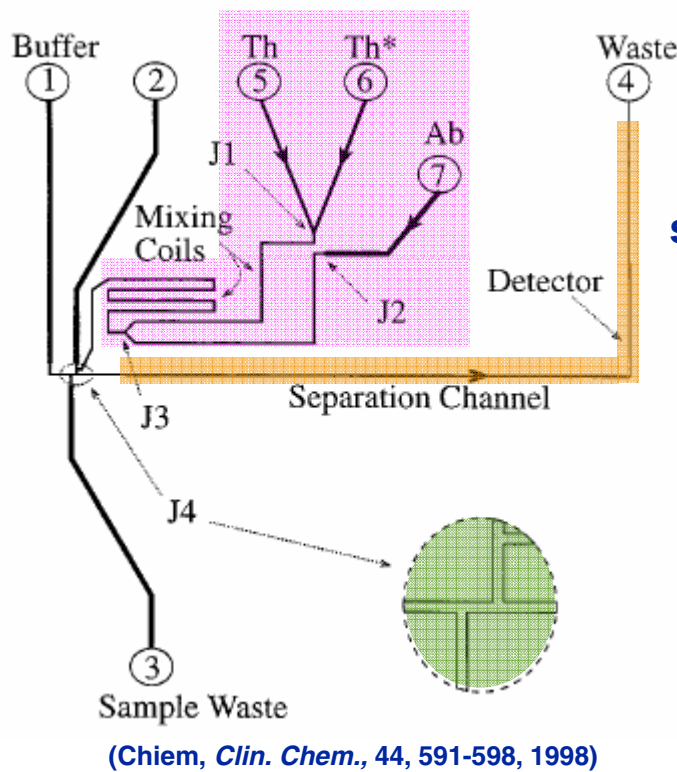
Spiral of five turns



Worst relative error 12% compared with experimental results

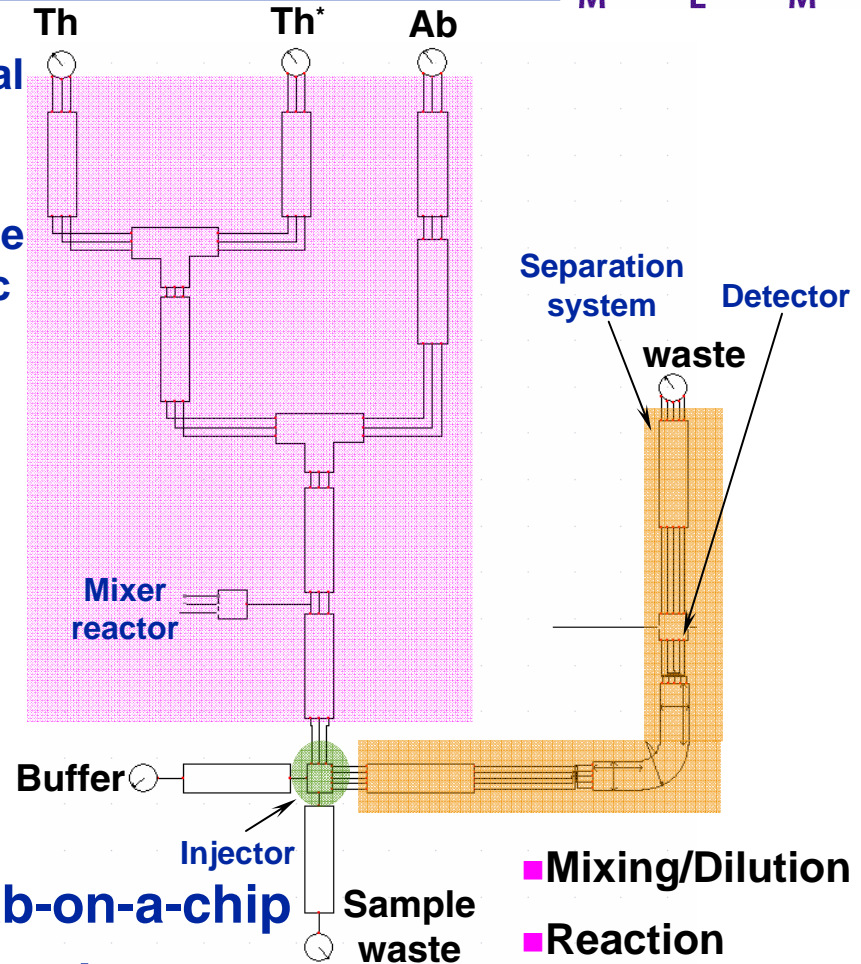
(C.T. Culbertson, S.C. Jacobson, J.M. Ramsey. *Anal. Chem.* 2000, 72, 5814-5819)

Simulation Framework of Lab on a Chip



behavioral model

 simulatable schematic



Separation system
 Detector
 waste

- Mixing/Dilution
- Reaction
- Injection
- Separation
- Detection

- First simulation on complete on Lab-on-a-chip
- Verilog-A simulated by Cadence/Spectre
- Two simulation phases
 - Loading (Mixing, reaction and injector loading)
 - Dispensing (injector dispensing, separation, detection)

Conclusion

- A composable system simulation framework built for biofluidic lab-on-a-chip
- Behavioral Models implemented in analog hardware description language (Verilog-A)
- Simulation results verified numerically and experimentally (relative error $\sim < 10\%$)
- A tremendous speedup (10~15,000X) achieved

Acknowledgements

- DARPA
- NSF