Mutiple DC Solution Determination using VHDL-AMS

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Problem and Proposed Approach

The investigation of nonlinear resistive networks is one of the fundamental tasks in circuit simulation. Relative difficult problems that have to be solved are:

- Finding the multiple DC solutions of circuits as flip-flops, Schmitttriggers, and negative resistance circuits.
- Calculation of multivalued transfer characteristics of nonlinear resistive networks (e.g. of Schmitt-triggers).
- Calculation of the turning points of multivalued transfer characteristics (e.g. in order to determine hysteresis or pull-in voltages in electromechanical systems).

Continuation techniques based on homotopy methods are typically applied to solve these problems whereas these methods are implemented in customized simulators

Proposed way in the presented paper:

- Direct application of the homotopy idea to the network analysis problem by creating a modified and augmented network that is similar to the original one.
- Constitutive relation of the modified subnets can be expressed using a behavioral description language, e. g. VHDL-AMS.
- Solution of the modified network using an available VHDL-AMS simulation engine. From the solution of the modified and augmented network we get the solution we are interested in.

An advantage of the suggested approach is that no special simulation engine is necessary. All features of available VHDL-AMS simulation engines can be used.

Homotopy Methods

- For the analysis of nonlinear resistive networks a system of nonlinear equations has to be solved: F(x)=0 ,where $\ F:R^n\to R^n$
- Continuation methods based on a homotopy function
- $H : \mathbb{R}^n \times \mathbb{R} \to \mathbb{R}^n$ with the following characteristics:
- The solution $x_0 \in \mathbb{R}^n$ of $H(x_0, \lambda_0) = 0$ can be determined for a given $\lambda_0 \in \mathbb{R}$.
- For a special $\lambda_f \in \mathbb{R}$ the solution $x_f \in \mathbb{R}^n$ of $H(x_f, \lambda_f) = 0$ is also a solution of F, i. e. $F(x_f) = 0$.
- The solution is calculated by following the solution curve $L = \{ (x, \lambda) \in \mathbb{R}^n \times \mathbb{R} \mid H(x, \lambda) = 0 \}$
 - from (x₀, λ_0) to (x_f, λ_f).
- L can be traced for instance by solving the following DAE $\begin{array}{ll} H\left(x,\,\lambda\right) &= 0 \\ \sum_{i\in I} x_{i}^{\,\prime}(t)^{2} + \lambda^{\prime}(t)^{2} &= 1, \quad \text{where } (x(0),\,\lambda(0)) = (x_{0},\,\lambda_{0}). \end{array}$

I is a set of essential variables for curve tracing. t is a pseudo arc length of the solution curve L.

Network Formulation

- Assume a resistive network N is given. We construct a modified network N_{λ} that is close-by the original. λ is an additional quantity. N is in accordance with F. N_{λ} corresponds to the homotopy function H
- To calculate the DC operating point, the modification can be done for instance by
 - Replacement of independent voltage and current sources with values V_{cl} and I_{cl} resp. by sources with values $\lambda^{.}\mathsf{V}_{cl}$ and λI_{cl} (source stepping).
 - Replacement of open branches by additional current sources with values $(1-\lambda) I_{c0}$ (artificial input current source stepping). ... G-min stepping, ...
- Operating points can be detected in these cases for $\lambda = 1$.
- N_{λ} is augmented by a subsystem that realizes the equation $\sum_{i \in I} pr_i x'(t)^2 + \lambda'(t)^2 = 0$. The output λ of this subsystem drives the modified sources and conductances.
- The augmented network can be evaluated with the time domain simulation algorithm of the simulation engine. The condition $\lambda=1$ can be detected using the 'ABOVE attribute of VHDL-AMS.
- Determination of transfer characteristics and turning points can be done in an equivalent manner.

Network Modifications (N_λ) entity css is generic (vc0 : real := 0.0); port(terminal p. m : electrical; quantity lambda : in real); end entity css; architecture al of trace is quantity lambda_dot : real; quantity x_help, x_dot : real_vector (1 to N); architecture a0 of css is signal i0 : real; quantity v across i through p to m; segin function factor (t: real; ta : real; tb : real) return real is variable th : real; X : real; begin begin th := (t-ta)/(tb-ta); return (3.0*th*th - 2.0*th*th*th); end function factor; process(domain) is begin i0 <= i; end process; if domain = quies v == vc0; nt_domain **use** Model realizes $\sum_{i \in I} x_i'(t)^2 + \lambda'(t)^2 = 1$ i == (1.0-lambda)*i0; end use; р of $(1-\lambda) I_0$ end architecture a0;

end use; and architecture a1;

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Artificial input current source

Multiple DC Solutions (Two-Tunnel-Diode Circuit)



Subcircuit to detect $\lambda = 1$ (driven by λ , observes voltage at p voltage)



Determination of Turning Points (Pull-in Voltage Calculation)



Subcircuit to detect the turning point



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