



Electronics & Computer Science
University of Southampton

Behavioural Simulation of Biological Neuron Systems using VHDL and VHDL-AMS

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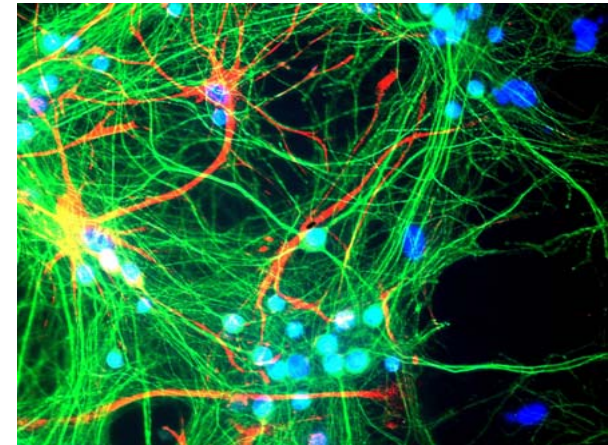
Presentation Outline

- [Introduction](#)
- The Nervous System
- Modelling Neurons
- Model Verification & Simulation Results
- Current & Future Work



Introduction

- Biologists & Engineers
- Characterising
 - Single Neurons
 - Network Behaviour
- Biological experiments
 - Live Tissue
 - Electrodes
- Modelling
 - Test Hypotheses



Stained Rat Cortical Neurons [1]



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Motivation

- Modelling Neuronal Systems
 - Look at whole animals
- Virtual Experiments
 - More than neurons
- Translate to hardware
 - Real-Time Simulation!

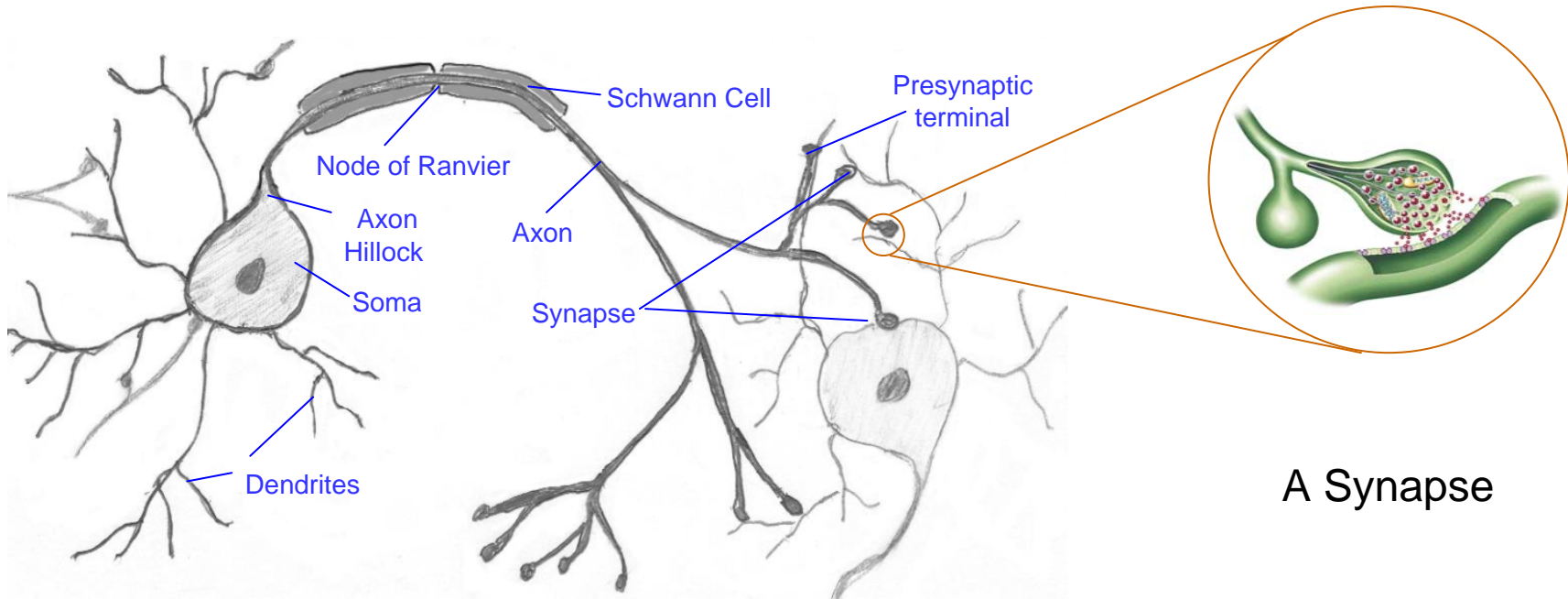




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- Simulation Methods & Simulation Results
- Current & Future Work



A Typical Neuron



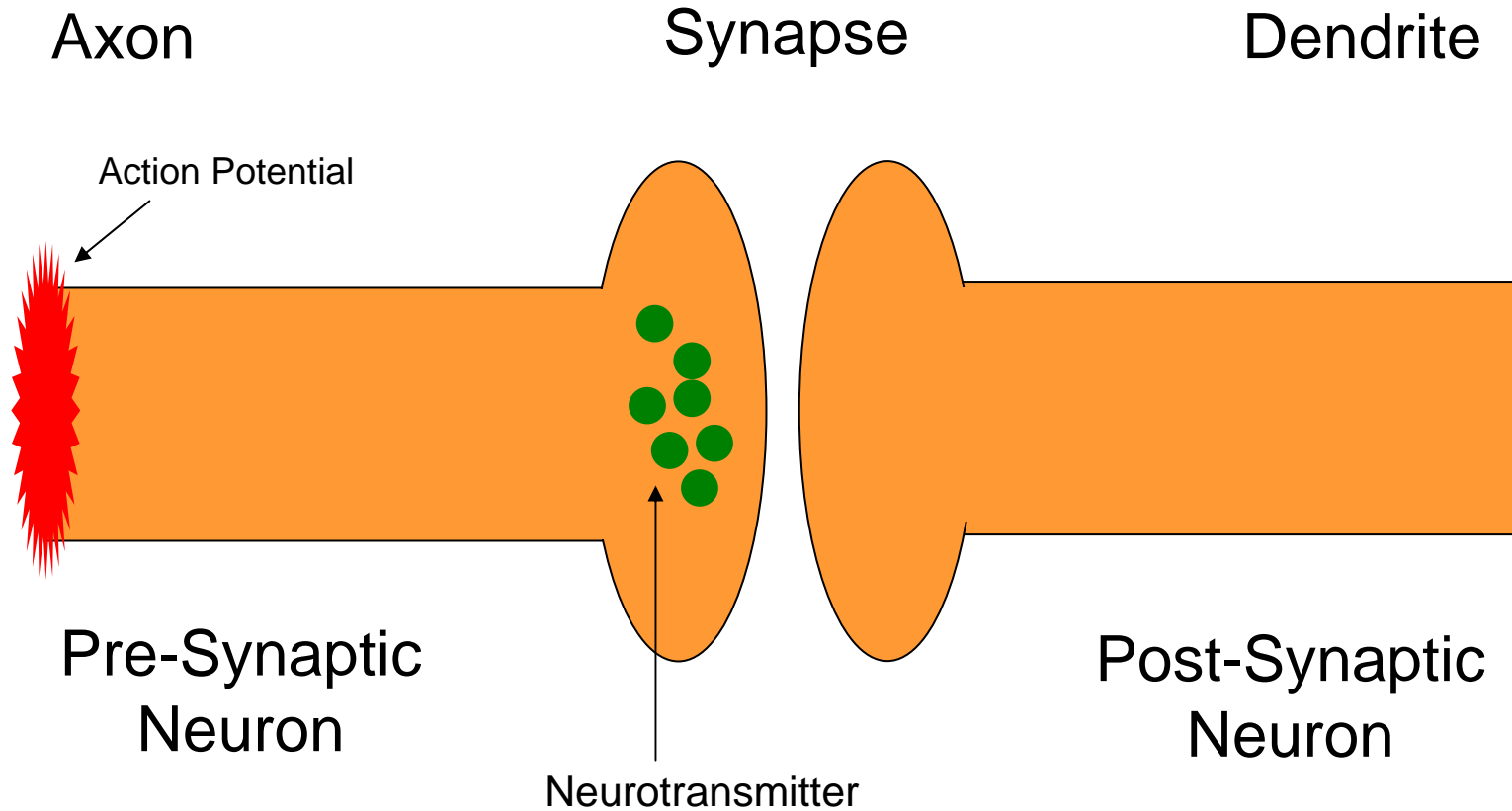
A Typical Neuron

A Synapse





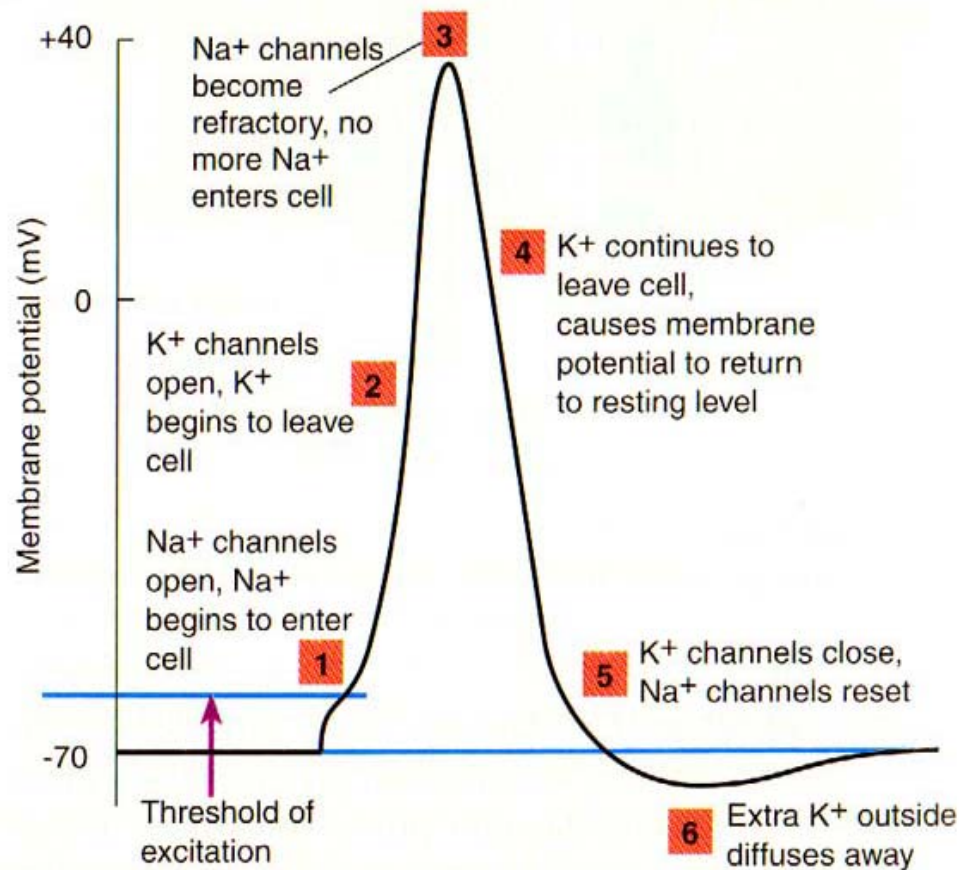
Neuron Signalling





Neuron Function

- Receives signals simultaneously
- Makes “Decisions”
- Modulates activity
- Information
 - Action Potentials



Phases of an Action Potential [1]

[1] – R. McCready, “Anatomy & Physiology Review: NEUROLOGICAL SYSTEM”, London Health Sciences Centre, January 2007.
http://gargoyle.arcadia.edu/psychology/blustein/neuro/Lecture_Notes/Week_1/Week_2/Action_Potential.jpg

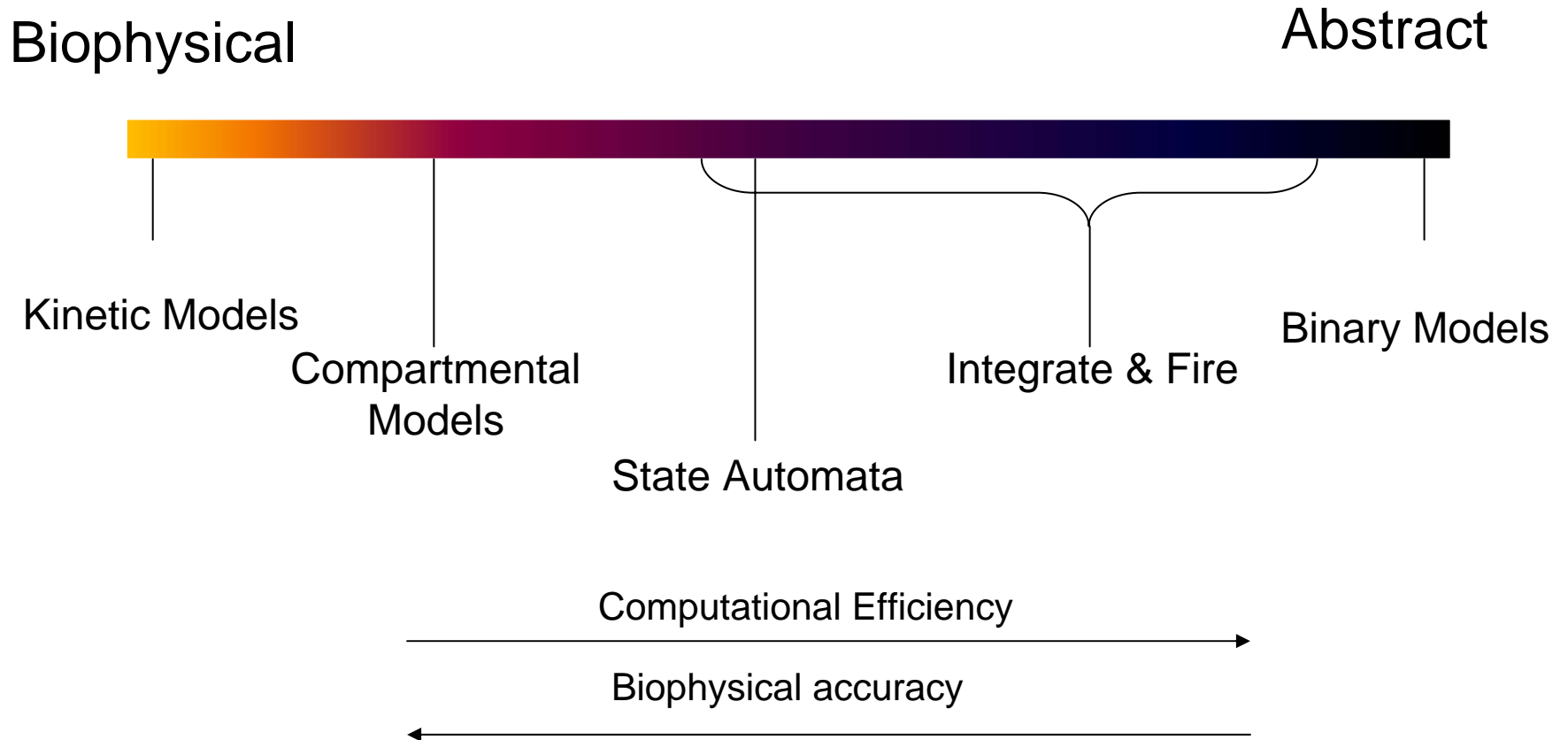




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Scale of Modelling



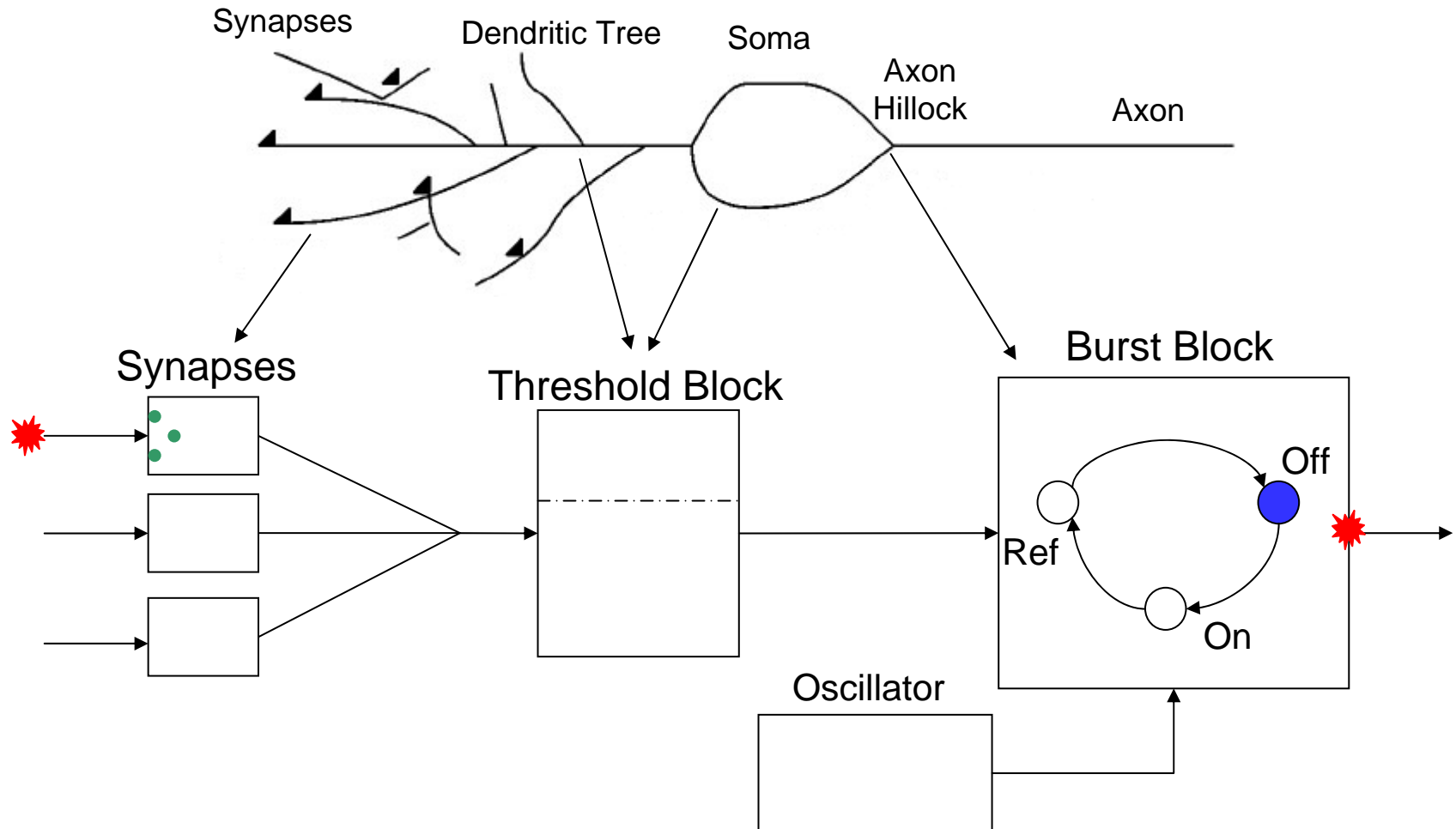


State Automata Models

- Good Balance
- Translation into Hardware
- Previous Experience
- Past Work
 - E.T. Claverol, A.D. Brown & J.E. Chad, "Scalable Cortical Simulations on Beowulf Architectures", Neurocomputing, 43, pp 307 – 315, Mar 2002.
 - E.T. Claverol, A.D. Brown & J.E. Chad, "Discrete Simulation of large aggregates of neurons", Neurocomputing, 47, pp 277-297, Oct 2002.
 - E.T. Claverol, A.D. Brown & J.E. Chad, "A Large Scale Simulation by a cell automaton based network model", IEEE Trans. Biomed. Eng., 49(9), pp 921-935, Sept 2002.



The Model





Choosing a Platform

- System C
 - Based on C/C++
 - Open-Source (Free)

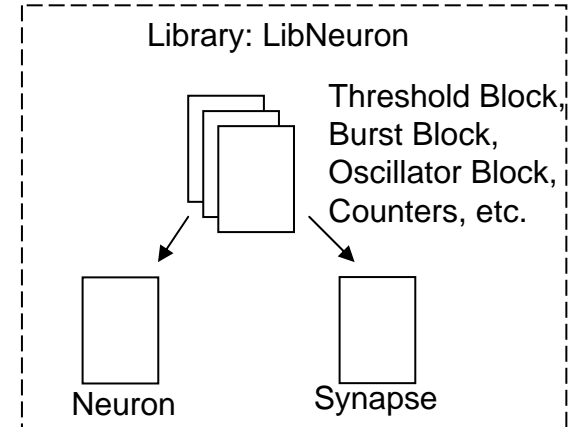
- VHDL
 - Mature Platform
 - AMS extensions
 - Simulating Hardware
 - Potential for Hardware Implementation

- Previous Work
 - S.S. Modi, P.R. Wilson, A.D. Brown & J.E. Chad, "Behavioural Simulation of Biological Neuron Systems in System C", *Proc. IEEE Workshop on Behavioural Modelling and Simulation (BMAS)*, pp 31-36, 2004
 - D. Sotiriou, "Implementation of Neuron Models in VHDL", MSc Report 2003



VHDL Implementation

- Standard Components Library
- Top Level Entities
 - Neuron
 - Synapse
- Configurable
- Nervous System Components



```
generic(NumberSynapses : Positive;  
        The           : Real;  
        THi           : Real;  
        Nburst        : Real;  
        Tap           : Time;  
        Tref          : Time  
);
```

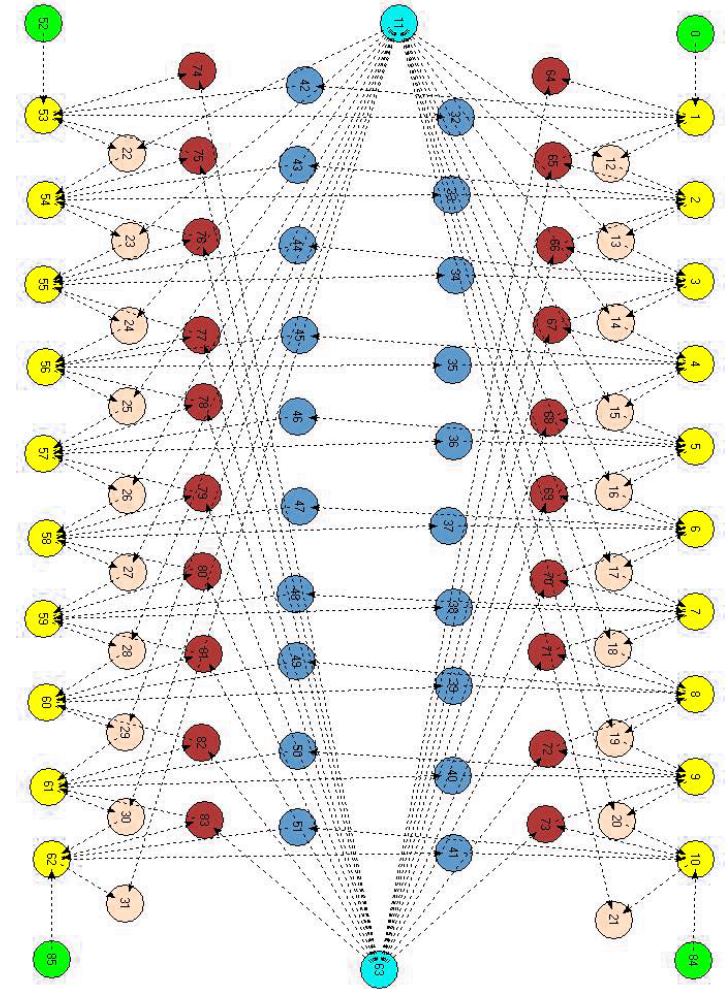


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Model Verification

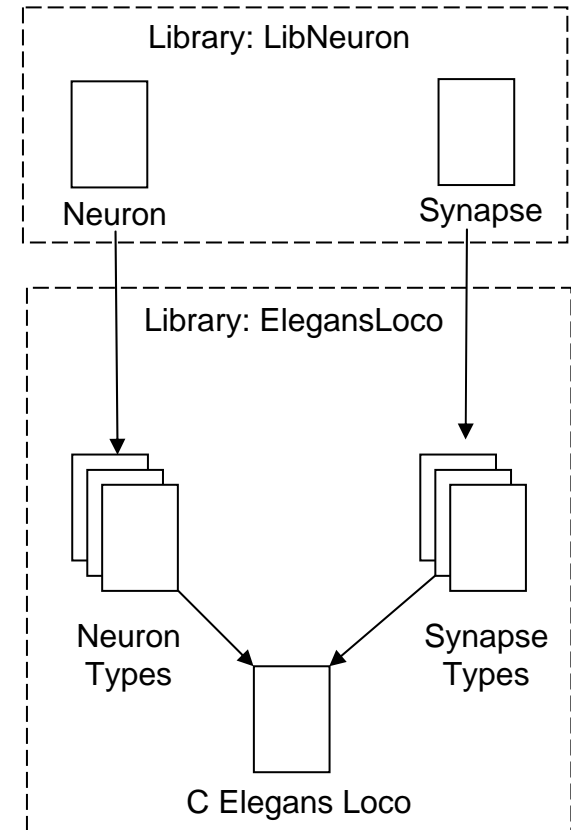
- Nematode, C Elegans
 - 1 mm long, 80 microns wide
 - 302 Neurons
 - Extensively studied
 - Connections partially known
 - Locomotion system
 - 85 neurons, approx 164 Synapses
 - Regular connection pattern





C Elegans VHDL

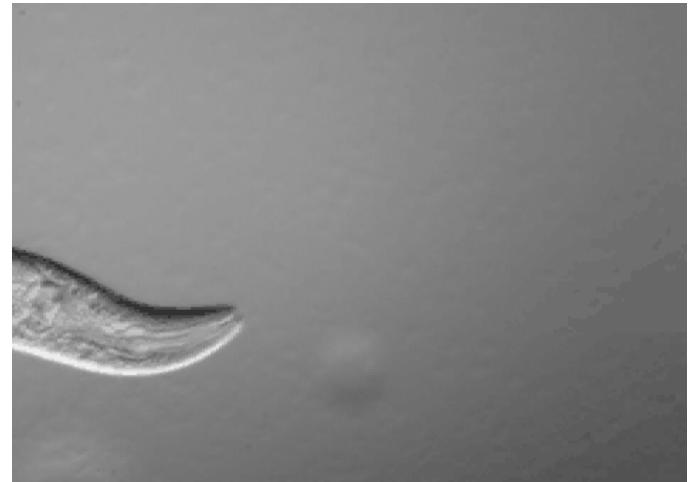
- Animal Library
 - ElegansLoco
- Specifies Generics
 - Creates Types
- Complexity Hidden





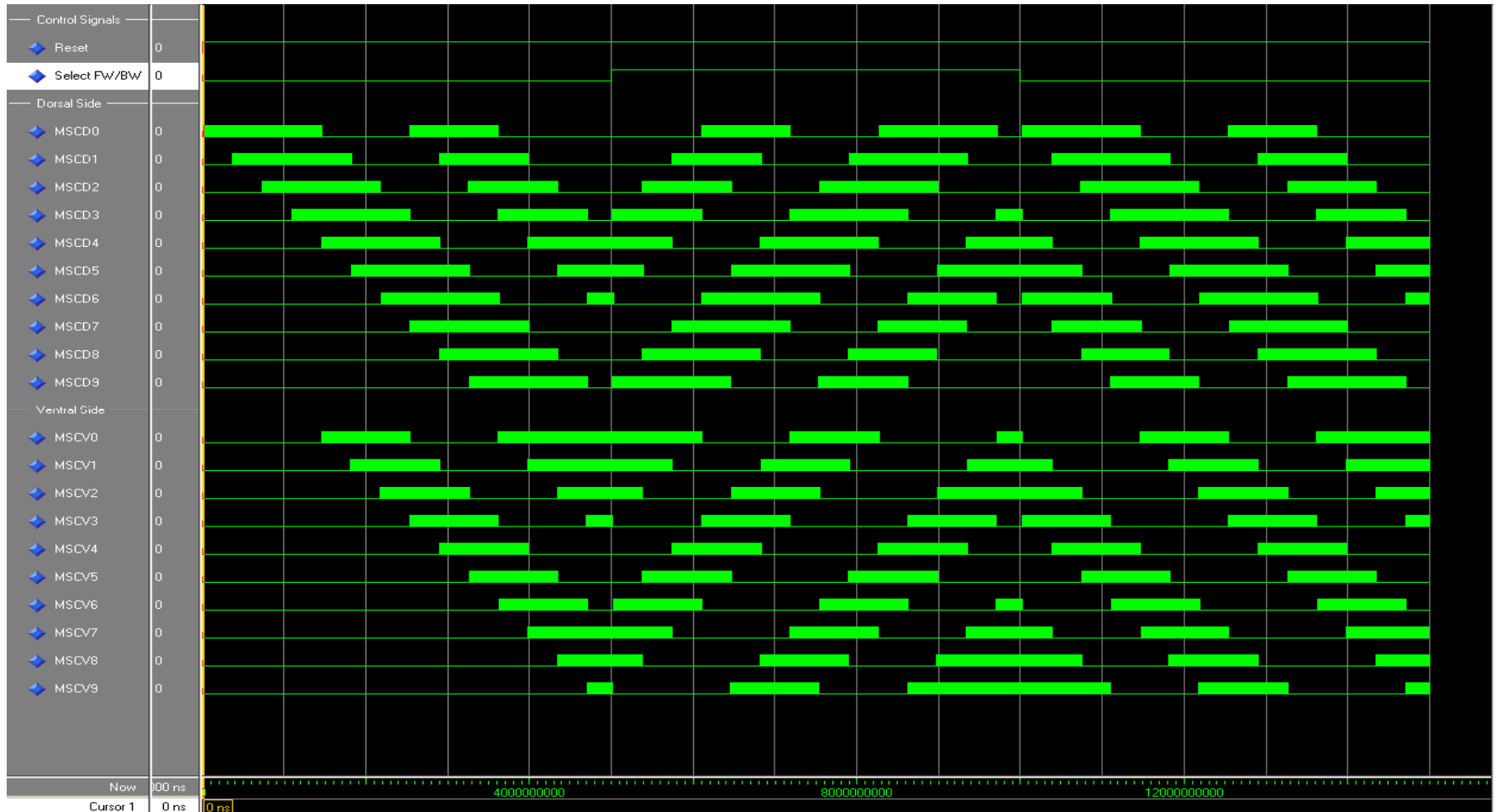
Previous results

- Previous results
 - System C
- C Elegans Videos
- Verification VHDL





Simulation Results



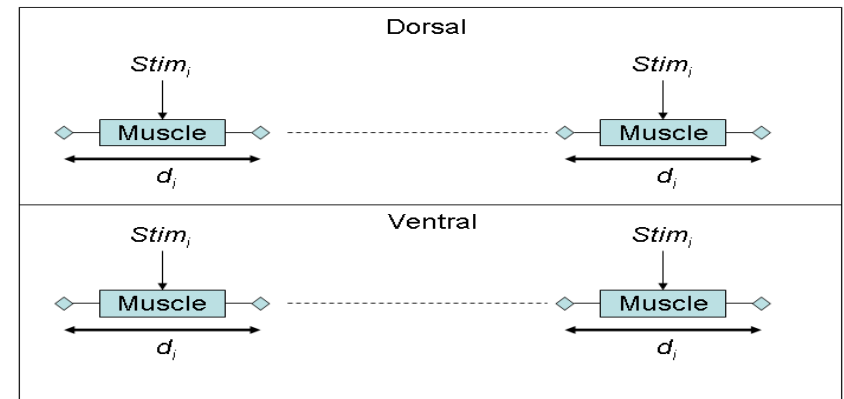
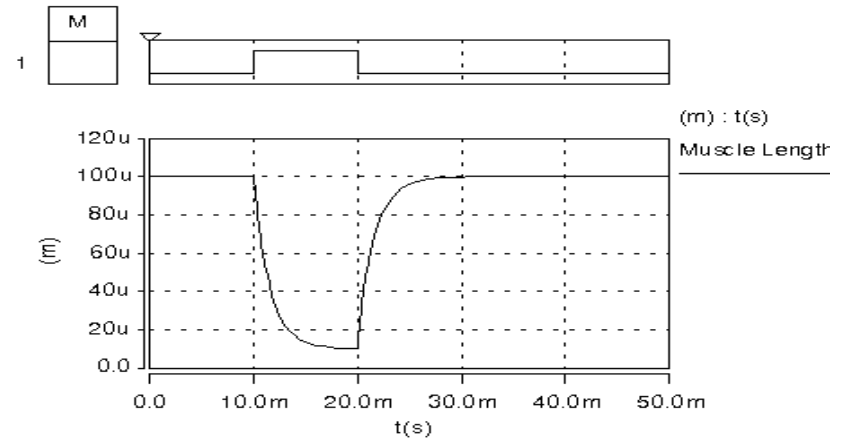


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VHDL-AMS

- Muscles
 - Complex Entities
 - Model Behaviour
- C Elegans Body Model
- Sensory Information
 - Chemical Gradients
- Virtual Experiments





Synthesis

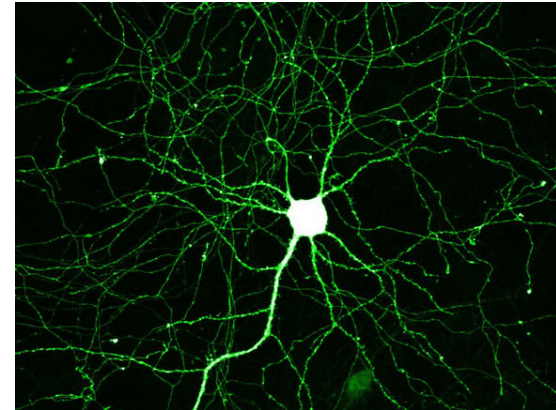
→ Synthesis to Hardware

→ Single Neuron

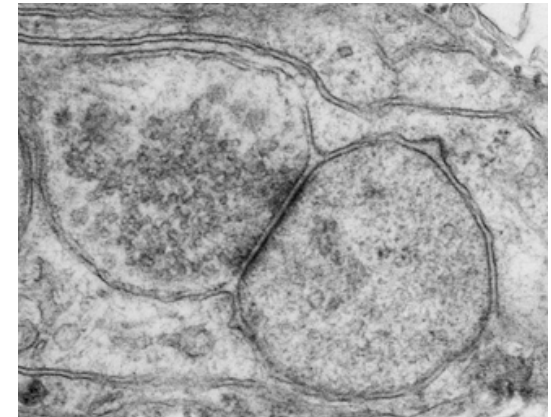
- 330 - 411 Function Generators
- 143 - 116 D-Type Flip-Flops

→ Single Synapse

- 1053 Function Generators
- 446 D-Type Flip-Flops



Stained Hippocampal Neuron [1]



SEM image of a Synapse [2]

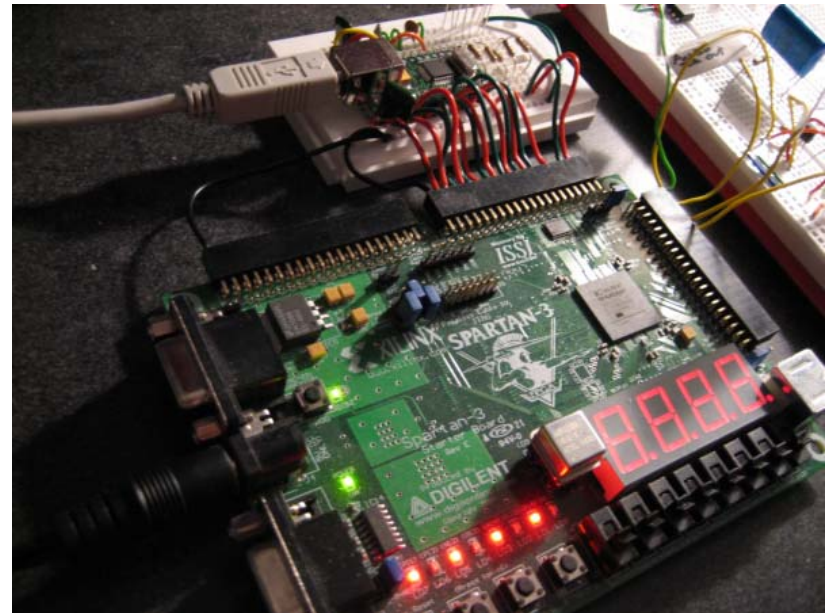
[1] - EnCor Biotechnology 2003, <http://strangepaths.com/wp-content/uploads/2006/10/neuron.jpg>

[2] - City of Hope National Medical Center and Beckman Research Institute,
<http://www.cityofhope.org/NR/rdonlyres/6683468D-846E-470F-8732-31AA8841673C/0/NeuronalSynapse.jpg>



Synthesis

- C Elegans Locomotion Design
 - Very Large (Approx. 201,558 FGs, 85,280 DFFs)
- What happens after synthesis?
 - Watch activity on oscilloscope
 - Easily Compare to Simulations
 - Interface to PC
 - Real-Time Simulation
 - Hardware Accelerator





On-Going Work

→ Mechanical Body Model – C Elegans

→ Synthesis to Hardware

- Interface to PC
- Hardware Acceleration



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Summary

- State Automata Model
 - VHDL Library – LibNeuron
- C Elegans Locomotion System
 - Verified against previous work
- VHDL-AMS Behavioural Muscle Model
 - Verified against Experiments
 - Mechanical Body Model
- Synthesis to Hardware
 - Hardware Acceleration of Simulations



Thanks For Listening!

→ Any Questions ?