

FULL SYSTEM VERIFICATION OF CAN NETWORK AT HIGH SPEED TRANSMISSION RATE USING VHDL-AMS

Thang Nguyen – KAI GmbH Martin Durreger – Carinthian Univeristy of Applied Science Georg Pelz – Infineon Technologies AG

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Never stop thinking

Agenda

- Motivation
- The CAN measurement system setup
- Modeling of the CAN physical layer
- Modeling of the measurement environment
- Verification of star network at 500 kb/s and 1.0 Mb/s
- Simulation of the CAN Micro-controller interface
- Conclusion and Outlook

Background - The CAN Protocol

Without CAN



With CAN ٧O NO. 1111111 1111111 unit NO unit 1111111 unit ıo ∎ unit ECU unit 1111111 UO. unit TITTTT NO.



CAN Physical Layer Design Challenges

• Implementation of networks:

- Hardware CAN components
- Termination
- Topologies
- The main objective in analyzing the physical layer is to identify and evaluate signal integrity issues
- The transmit and receive waveforms need to be checked against the system specification :
 - Safe transmission must be ensured
 - Problems at this layer can:
 - impact the entire communication system,
 - reduce the network performance
 - or cause errors in the control system behavior
 - Network reliability will be compromised

A comprehensive and reliable simulation solution is required

Motivation

- Verify the accuracy of CAN physical layer simulation models against real measurement at system level
- Star topology neither covered by ISO11898 nor by SAE J2284 - used in automotive applications to overcome wiring constrains within a car.
- Prove the feasibility of a specific topology by simulations and measurements on a system setup

Components of CAN Physical Layer



The CAN measurement system setup







Modeling of the CAN Physical Layer

• The CAN Transceiver model:



- has a complex structure
- covers temperature monitoring
- covers bus failure detection

- The choke coil model \rightarrow based on its SPICE model
- The transmission line model
 - Characteristic impedance, propagation delays, length
 - \rightarrow Cable tree (the star network topology)

Modeling of the CAN Measurement Environment

Measurement probe model



passive probe model (R_{in}=10M;C_{in}=9.5pF)

active probe model (R_{in}=1.0M;C_{in}=0.95pF)

- The CAN triggering module model
- The CAN frame generator model
 - CAN transmission speed
 - Rising/Falling time of TxD signal

Simulation of the 24-node star network



compatible with ISO
11898 CAN 2.0A and SAE
J2289

- un-equal stub length
- 500 kb/s trans. rate
- split termination circuit at star connection point
- total cable length 58.0 m

Verification of 24-node star network at 500 kbps transmission rate



Verification of 8-node star network at 1.0 Mbps transmission rate



Simulation of Tx and Rx signals of the CAN Micro-controller interface

By measurement setup:

- RM is connected to 5.0V
- INH is connected to ground
 → Normal mode



By simulation setup:

Standby mode → Normal mode

 \rightarrow RM and INH signals is modelled by a piecewise linear voltage source (V_PWL)

Simulation of Tx and Rx signals of the CAN Micro-controller interface – Result 1



Simulation of Tx and Rx signals of the CAN Micro-controller interface – Result 2



Conclusion

- Small deviation between measurement and simulation → the simulation models are accurate
- Implemented star topology shows a stable behavior of electrical signal on the CAN bus
- Models of CAN measurement environment must be taken into consideration
- It is possible to simulate up to the interface of the CAN microcontroller without having to model and simulate the CAN controller.

Future work

- Non-standard CAN network topologies validation
- Bus error detection under
 - Extreme temperature condition
 - Maximum number of nodes vs. high speed transmission rate
- Provide methodology for automation of CAN physical layer verification of complex network

Non-standard CAN network topologies



Thank you for your attention